

# Effective Medium Model for Multilayered Anisotropic Media with Different Orientations

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**Abstract** — An efficient model is developed to simulate multilayered biaxial anisotropic material with different orientations by using effective medium theory. Equivalent model is used to extract effective permittivity, permeability and orientation angle for multilayered biaxial anisotropic medium. Analytical expressions for effective parameters and orientation angle are derived for low frequency (LF) limit. The model also gives a non-magnetic effective anisotropic layer if each layer is non-magnetic anisotropic dielectric. Good agreement is achieved by comparing the effective parameters extracted with and without low frequency approximation. We show that the frequency-independent equivalent model is valid for frequency up to 10 GHz.

**Index Terms** — Effective medium theory, multilayered anisotropic media, parameter extraction.

## I. INTRODUCTION

Anisotropic property is very popular among modern engineering materials such as composites, fibers, crystals, wood and so on. These kinds of materials have a lot of usages as housings and casings in aerospace, transportation, civil infrastructure, electronics, appliance and marine due to its characteristics such as: low weight, less tooling costs, high stiffness, low corrosion and easy to fabricate [1-5]. In aerospace industry, composites can be replacements for metals due to its good features that they are not as electrically conductive as traditional ones [2]. Thus, it becomes more and more important to understand the electromagnetic interactions (i.e., reflection, transmission) of composites [3, 5]. Multilayered anisotropic material with different orientations is very common in composites. However, electromagnetic modelling of multilayered anisotropic material needs huge CPU time and memory requirements. Using effective medium theory, by combining multilayered anisotropic medium with a single equivalent layer for the permittivity, permeability and orientation, CPU time and memory requirements can be significantly reduced [6].

In this paper, effective medium theory is applied to model multilayered biaxial anisotropic material with

different orientations for a plane wave incidence at the normal direction. Basing on the same reflection and transmission coefficients, effective permittivity, permeability and orientation angle are extracted, similar to the approach used to extract effective parameters from measurements and numerical modeling of periodic structures as isotropic materials. With the low frequency (LF) limit, analytical expressions for effective parameters and orientation angle are derived and result in a frequency-independent equivalent model. Finally, effective parameters using low frequency approximation are compared with the ones from parameter extraction method. Good agreements in effective parameters and angle are observed between with and without the approximations for the frequency up to 10 GHz.

## II. FORMULATION

In Fig. 1, the equivalent model is presented for multilayered biaxial anisotropic media with different orientations between two half spaces. A plane wave travels at the normal direction ( $z$  direction) to  $x$ - $y$  plane. A global Cartesian coordinate  $x$ - $y$ - $z$  is used in the two half spaces and local coordinate  $x'$ - $y'$ - $z$  for each layer between two half spaces with  $x'_n$  rotating  $\theta_n$  from  $x$ . The relative permeability and permittivity of the biaxial anisotropic layer can be expressed in tensor form as  $\bar{\mu}_n = \text{diag}(\mu_{xn}, \mu_{yn}, \mu_{zn})$ ,  $\bar{\epsilon}_n = \text{diag}(\epsilon_{xn}, \epsilon_{yn}, \epsilon_{zn})$ .

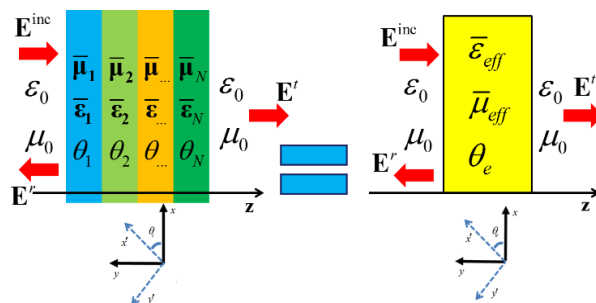


Fig. 1. Multilayered biaxial anisotropic media and its equivalent single layer model.

### A. Reflection and transmission coefficient for equivalent layer

For the equivalent layer model, suppose electromagnetic field propagates in  $z$  direction with electric field polarized in  $x$  and  $y$  directions. We can get reflection and transmission coefficient matrices by expressing the electromagnetic field in all three regions and matching boundary conditions. The reflection coefficient  $\mathbf{R}$  and transmission coefficient  $\mathbf{T}$  are 2 by 2 matrices and are defined similar to S parameters [7]:

$$\begin{aligned} R_{pp} &= A_p \cos^2 \theta_e + A_p \sin^2 \theta_e, \\ R_{yx} &= R_{xy} = (A_x - A_y) \sin \theta_e \cos \theta_e, \\ T_{pp} &= B_p \cos^2 \theta_e + B_p \sin^2 \theta_e, \\ T_{yx} &= T_{xy} = (B_x - B_y) \sin \theta_e \cos \theta_e, \end{aligned} \quad (1)$$

where

$$A_p = \frac{\Gamma_{0p}(1 - e^{-2j\beta_p d_t})}{1 - \Gamma_{0p}^2 e^{-2j\beta_p d_t}}, \quad B_p = \frac{(1 - \Gamma_{0p}^2) e^{-j\beta_p d_t}}{1 - \Gamma_{0p}^2 e^{-2j\beta_p d_t}}, \quad \Gamma_{0p} = \frac{\tilde{\eta}_p - 1}{\tilde{\eta}_p + 1},$$

$$\beta_p = \beta_0 \sqrt{\varepsilon_{pe} \mu_{pe}}, \quad \tilde{\eta}_p = \sqrt{\frac{\mu_{pe}}{\varepsilon_{pe}}}, \quad p = x, y, \quad \tilde{p} = \begin{cases} x, & p = y \\ y, & p = x \end{cases}$$

$A_p$  and  $B_p$  are the same as the reflection and transmission coefficients derived using isotropic layer with  $\mu_{\tilde{p}}$  and  $\varepsilon_p$ .  $d_t$  is the total thickness and  $\beta_0 = \omega \sqrt{\varepsilon_0 \mu_0}$ .

### B. Reflection and transmission coefficients for multilayers

The first method to derive the reflection and transmission matrices is similar to the transmission line theory. For region  $n$  (1 to  $N$ ),  $z_n < z < z_{n+1}$ ,  $z$  there are two types of propagation modes in local coordinate:

$$\mathbf{E}_n = \begin{bmatrix} E_{nx'} \\ E_{ny'} \end{bmatrix} = \left[ e^{-j\tilde{\beta}_n(z-z_{n+1})} + e^{j\tilde{\beta}_n(z-z_{n+1})} \bar{\mathbf{R}}_{n,n+1}^- \right] \begin{bmatrix} A_n \\ B_n \end{bmatrix}, \quad (2)$$

$$\begin{aligned} \eta_0 \bar{\mathbf{Z}}_{n0} \cdot \mathbf{H}_n &= \eta_0 \begin{bmatrix} \eta_{nx} & 0 \\ 0 & \eta_{ny} \end{bmatrix} \begin{bmatrix} H_{ny'} \\ -H_{nx'} \end{bmatrix} \\ &= \left[ e^{-j\tilde{\beta}_n(z-z_{n+1})} - e^{j\tilde{\beta}_n(z-z_{n+1})} \bar{\mathbf{R}}_{n,n+1}^- \right] \begin{bmatrix} A_n \\ B_n \end{bmatrix}, \end{aligned} \quad (3)$$

where  $\bar{\mathbf{Z}}_{n0} = \text{diag}(\eta_{nx}, \eta_{ny})$ ,  $\tilde{\beta}_n = \text{diag}(\beta_{nx}, \beta_{ny})$ ,  $\bar{\mathbf{R}}_{n,n+1}^-$  is the 2 by 2 reflection matrix in region  $n$  at  $z_{n+1}$ .

The fields also can be written in the global coordinate

$$\begin{bmatrix} E_{nx'} \\ E_{ny'} \end{bmatrix} = \bar{\mathbf{O}}_n \begin{bmatrix} E_{nx} \\ E_{ny} \end{bmatrix}, \quad \begin{bmatrix} H_{ny'} \\ -H_{nx'} \end{bmatrix} = \bar{\mathbf{O}}_n \begin{bmatrix} H_{ny} \\ -H_{nx} \end{bmatrix}, \quad (4)$$

where the rotation matrix  $\bar{\mathbf{O}}_n$  is given as:

$$\bar{\mathbf{O}}_n = \begin{bmatrix} \cos \theta_n & \sin \theta_n \\ -\sin \theta_n & \cos \theta_n \end{bmatrix}, \quad \bar{\mathbf{O}}_n^{-1} = \bar{\mathbf{O}}_n^T. \quad (5)$$

The relation between the electric and magnetic fields at

$z = z_{n+1}$  is:

$$\mathbf{E}_n(z_{n+1}) = \eta_0 \bar{\mathbf{Z}}_{n,n+1}^- \cdot \mathbf{H}_n(z_{n+1}), \quad (6)$$

$\bar{\mathbf{Z}}_{n,n+1}^-$  is the input impedance at  $z = z_{n+1}$ . Submitting (2) and (3) into (6) yields:

$$\bar{\mathbf{R}}_{n,n+1}^- = \left[ \bar{\mathbf{Z}}_{n,n+1}^- \bar{\mathbf{Z}}_{n0}^{-1} + \bar{\mathbf{I}} \right]^{-1} \left[ \bar{\mathbf{Z}}_{n,n+1}^- \bar{\mathbf{Z}}_{n0}^{-1} - \bar{\mathbf{I}} \right], \quad (7)$$

where  $\bar{\mathbf{I}} = \text{diag}(1,1)$  and matrix multiplications are involved. At  $z = z_n$ , similarly, we have:

$$\mathbf{E}_n(z_n) = \eta_0 \bar{\mathbf{Z}}_{n-1,n}^+ \cdot \mathbf{H}_n(z_n). \quad (8)$$

It is found that,

$$\begin{aligned} \bar{\mathbf{Z}}_{n-1,n}^+ &= \left[ \bar{\mathbf{I}} + e^{-j\tilde{\beta}_n d_n} \bar{\mathbf{R}}_{n,n+1}^- e^{-j\tilde{\beta}_n d_n} \right] \\ &\cdot \left[ \bar{\mathbf{I}} - e^{-j\tilde{\beta}_n d_n} \bar{\mathbf{R}}_{n,n+1}^- e^{-j\tilde{\beta}_n d_n} \right]^{-1} \bar{\mathbf{Z}}_{n0}, \end{aligned} \quad (9)$$

where  $d_n = z_{n+1} - z_n$ . At the interface, the tangential components of both electric and magnetic fields should be continuous. Using the equations above, we find the impedance matrices at two sides and field components as:

$$\begin{aligned} \bar{\mathbf{Z}}_{n-1,n}^- &= \bar{\mathbf{O}}_{n-1} \bar{\mathbf{O}}_n^T \bar{\mathbf{Z}}_{n-1,n}^+ \bar{\mathbf{O}}_n \bar{\mathbf{O}}_{n-1}^T, \\ \begin{bmatrix} A_n \\ B_n \end{bmatrix} &= e^{-j\tilde{\beta}_n d_n} \left[ \bar{\mathbf{I}} + e^{-j\tilde{\beta}_n d_n} \bar{\mathbf{R}}_{n,n+1}^- e^{-j\tilde{\beta}_n d_n} \right]^{-1} \\ &\cdot \bar{\mathbf{O}}_n \bar{\mathbf{O}}_{n-1}^T \left[ \bar{\mathbf{I}} + \bar{\mathbf{R}}_{n-1,n}^- \right] \begin{bmatrix} A_{n-1} \\ B_{n-1} \end{bmatrix}. \end{aligned} \quad (10)$$

In Region 0, which is the half-space for the incident wave, the electric field is written as:

$$\mathbf{E}_0 = \begin{bmatrix} E_{0x} \\ E_{0y} \end{bmatrix} = \left[ e^{-j\tilde{\beta}_0(z-z_1)} + e^{-j\tilde{\beta}_0(z-z_1)} \bar{\mathbf{R}} \right] \begin{bmatrix} A_0 \\ B_0 \end{bmatrix}, \quad (11)$$

where  $\bar{\mathbf{R}} = \bar{\mathbf{R}}_{0,1}^-$  is the reflection matrix defined at  $z = z_1$  and can be calculated recursively using (10), (7) and (9) with  $\bar{\mathbf{Z}}_{N,N+1}^+ = \bar{\mathbf{Z}}_{(N+1)0} = \bar{\mathbf{I}}$ .

In the half-space Region  $N+1$ , the electric field is written as:

$$\mathbf{E}_{N+1} = \begin{bmatrix} E_{N+1,x} \\ E_{N+1,y} \end{bmatrix} = e^{-j\tilde{\beta}_0(z-z_{N+1})} \bar{\mathbf{T}} \begin{bmatrix} A_0 \\ B_0 \end{bmatrix}. \quad (12)$$

Using (11) recursively, the total transmission matrix defined at  $z = z_{N+1}$  is represented as:

$$\begin{aligned} \bar{\mathbf{T}} &= \bar{\mathbf{O}}_N^T \left[ \bar{\mathbf{I}} + \bar{\mathbf{R}}_{N,N+1}^- \right] \\ &\cdot \prod_{n=1}^N e^{-j\tilde{\beta}_n d_n} \left[ \bar{\mathbf{I}} + e^{-j\tilde{\beta}_n d_n} \bar{\mathbf{R}}_{n,n+1}^- e^{-j\tilde{\beta}_n d_n} \right]^{-1} \bar{\mathbf{O}}_n \bar{\mathbf{O}}_{n-1}^T \left[ \bar{\mathbf{I}} + \bar{\mathbf{R}}_{n-1,n}^- \right], \end{aligned} \quad (13)$$

where  $d_{N+1} = 0$ ,  $\bar{\mathbf{O}}_0 = \bar{\mathbf{O}}_{N+1} = \bar{\mathbf{I}}$ .

Another method to get total reflection and transmission coefficients for multilayers can be followed an approach in [8]. The basic idea is to calculate reflection and transmission coefficients from an

interface between two half spaces and then get total reflection and transmission coefficients recursively.

When Regions  $n$  and  $n+1$  are half-space, the electric and magnetic fields at the interface are written in local coordinates as:

$$\mathbf{E}_n = \begin{bmatrix} E_{nx'} \\ E_{ny'} \end{bmatrix} = [\bar{\mathbf{I}} + \bar{\mathbf{R}}_{n,n+1}] e^{-j\bar{\beta}_n d_n} \begin{bmatrix} A_n \\ B_n \end{bmatrix}, \quad (15)$$

$$\eta_{l0} \bar{\mathbf{Z}}_{n0} \cdot \mathbf{H}_n = [\bar{\mathbf{I}} - \bar{\mathbf{R}}_{n,n+1}] e^{-j\bar{\beta}_n d_n} \begin{bmatrix} A_n \\ B_n \end{bmatrix},$$

$$\mathbf{E}_{n+1} = \begin{bmatrix} E_{(n+1)x'} \\ E_{(n+1)y'} \end{bmatrix} = \bar{\mathbf{T}}_{n,n+1} e^{-j\bar{\beta}_n d_n} \begin{bmatrix} A_n \\ B_n \end{bmatrix}, \quad (16)$$

$$\eta_{l0} \bar{\mathbf{Z}}_{(n+1)0} \cdot \mathbf{H}_{(n+1)} = \bar{\mathbf{T}}_{n,n+1} e^{-j\bar{\beta}_n d_n} \begin{bmatrix} A_n \\ B_n \end{bmatrix}.$$

Matching the boundary conditions at the interface using the global coordinate yields:

$$\bar{\mathbf{O}}_n^T [\bar{\mathbf{I}} + \bar{\mathbf{R}}_{n,n+1}] = \bar{\mathbf{O}}_{n+1}^T \bar{\mathbf{T}}_{n,n+1}, \quad (17)$$

$$\bar{\mathbf{O}}_n^T \bar{\mathbf{Z}}_{n0}^{-1} [\bar{\mathbf{I}} - \bar{\mathbf{R}}_{n,n+1}] = \bar{\mathbf{O}}_{n+1}^T \bar{\mathbf{Z}}_{(n+1)0}^{-1} \bar{\mathbf{T}}_{n,n+1}. \quad (18)$$

The half-space reflection and transmission coefficients are found as:

$$\bar{\mathbf{R}}_{n,n+1} = [\bar{\mathbf{Z}}_{n0}^{-1} + \bar{\mathbf{O}}_n \bar{\mathbf{O}}_n^T \bar{\mathbf{Z}}_{(n+1)0}^{-1} \bar{\mathbf{O}}_{n+1} \bar{\mathbf{O}}_n^T]^{-1} \cdot [\bar{\mathbf{Z}}_{n0}^{-1} - \bar{\mathbf{O}}_n \bar{\mathbf{O}}_n^T \bar{\mathbf{Z}}_{(n+1)0}^{-1} \bar{\mathbf{O}}_{n+1} \bar{\mathbf{O}}_n^T], \quad (19)$$

$$\begin{aligned} \bar{\mathbf{T}}_{n,n+1} &= \bar{\mathbf{O}}_{n+1} \bar{\mathbf{O}}_n^T [\bar{\mathbf{I}} + \bar{\mathbf{R}}_{n,n+1}] \\ &= 2\bar{\mathbf{O}}_{n+1} \bar{\mathbf{O}}_n^T [\bar{\mathbf{Z}}_{n0}^{-1} + \bar{\mathbf{O}}_n \bar{\mathbf{O}}_n^T \bar{\mathbf{Z}}_{(n+1)0}^{-1} \bar{\mathbf{O}}_{n+1} \bar{\mathbf{O}}_n^T]^{-1} \bar{\mathbf{Z}}_{n0}^{-1}. \end{aligned} \quad (20)$$

It can be verified that the reflection matrix is symmetrical, but the transmission matrix is not in general, and,

$$\bar{\mathbf{R}}_{n+1,n} = -\bar{\mathbf{O}}_{n+1} \bar{\mathbf{O}}_n^T \bar{\mathbf{R}}_{n,n+1} \bar{\mathbf{O}}_n \bar{\mathbf{O}}_{n+1}^T, \quad (21)$$

$$\bar{\mathbf{T}}_{n+1,n} = \bar{\mathbf{O}}_n \bar{\mathbf{O}}_{n+1}^T [\bar{\mathbf{I}} + \bar{\mathbf{R}}_{n+1,n}] = [\bar{\mathbf{I}} - \bar{\mathbf{R}}_{n,n+1}] \bar{\mathbf{O}}_n \bar{\mathbf{O}}_{n+1}^T. \quad (22)$$

The total reflection and transmission coefficients in [8] can be written as:

$$\begin{aligned} \bar{\mathbf{R}}_{n,n+1}^- &= \bar{\mathbf{R}}_{n,n+1} + \bar{\mathbf{T}}_{n+1,n} e^{-j\bar{\beta}_{n+1} d_{n+1}} \bar{\mathbf{R}}_{n+1,n+2}^- \\ &\cdot [\bar{\mathbf{I}} - e^{-j\bar{\beta}_{n+1} d_{n+1}} \bar{\mathbf{R}}_{n+1,n} e^{-j\bar{\beta}_{n+1} d_{n+1}} \bar{\mathbf{R}}_{n+1,n+2}^-]^{-1} e^{-j\bar{\beta}_{n+1} d_{n+1}} \bar{\mathbf{T}}_{n,n+1}, \end{aligned} \quad (23)$$

$$\bar{\mathbf{T}} = \bar{\mathbf{T}}_{N,N+1} \prod_{n=1}^N [\bar{\mathbf{I}} - e^{-j\bar{\beta}_n d_n} \bar{\mathbf{R}}_{n,n-1} e^{-j\bar{\beta}_n d_n} \bar{\mathbf{R}}_{n,n+1}^-]^{-1} e^{-j\bar{\beta}_n d_n} \bar{\mathbf{T}}_{n-1,n}. \quad (24)$$

### C. Equivalent model and low frequency approximation

Basing on same reflection and transmission coefficients for the single equivalent layer and multilayer, we express  $\theta_e$ ,  $A_p$  and  $B_p$  as functions of the reflection and transmission coefficients of multilayer structures:

$$\tan 2\theta_{er} = \frac{2R_{xy}}{R_{xx} - R_{yy}}, \quad (25)$$

$$\tan 2\theta_{et} = \frac{2\bar{T}_{xy}}{T_{xx} - T_{yy}},$$

$$A_{x,y} = \frac{1}{2} (R_{xx} + R_{yy}) \pm \frac{R_{xy}}{\sin 2\theta_{er}}, \quad (26)$$

$$B_{x,y} = \frac{1}{2} (T_{xx} + T_{yy}) \pm \frac{\bar{T}_{xy}}{\sin 2\theta_{et}},$$

where  $R_{xy} = R_{yx}$ ,  $T_{xy} \neq T_{yx}$ ,  $\bar{T}_{xy} = \frac{1}{2}(T_{xy} + T_{yx})$ , the “ $\pm$ ” is for  $x$ - and  $y$ -component, respectively.

Then the effective parameters of the effective medium can be calculated from  $A_p$  and  $B_p$  using the approach for the isotropic layer [9-13]. The flowchart summarizing this procedure is shown in Fig. 2.

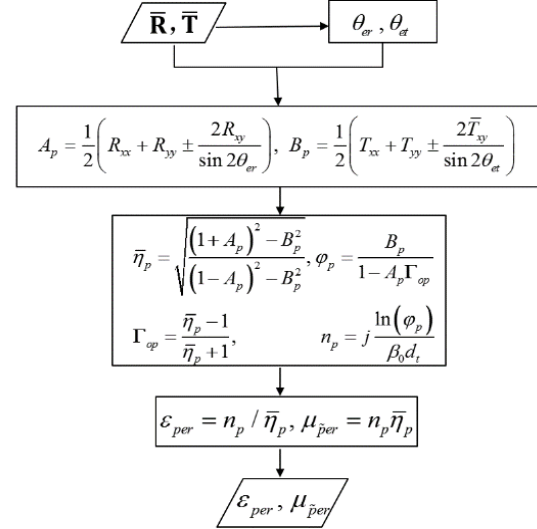


Fig. 2. Flowchart for effective parameters extraction.

For the low frequency limit, we follow the similar procedure to the isotropic case in [6]. The condition for low frequency approximation is satisfied when the wavelength is much bigger than the thickness of the structures. When  $\beta_{np} d_n \ll 1$ , applying Taylor series expansion to (9) and (14) and taking the first-order approximation yields:

$$e^{-j\bar{\beta}_n d_n} \approx \bar{\mathbf{I}} - j d_n \bar{\beta}_n. \quad (27)$$

Using  $\bar{\mathbf{Z}}_{N,N+1}^+ = \bar{\mathbf{Z}}_{(N+1)0} = \bar{\mathbf{I}}$ , we have:

$$\bar{\mathbf{Z}}_{N,N+1}^- = \bar{\mathbf{O}}_N \bar{\mathbf{O}}_{N+1}^T \bar{\mathbf{Z}}_{N,N+1}^+ \bar{\mathbf{O}}_{N+1} \bar{\mathbf{O}}_N^T = \bar{\mathbf{I}}, \quad (28)$$

$$\bar{\mathbf{R}}_{N,N+1}^- = [\bar{\mathbf{Z}}_{N,N+1}^- \bar{\mathbf{Z}}_{N0}^{-1} + \bar{\mathbf{I}}]^{-1} [\bar{\mathbf{Z}}_{N,N+1}^- \bar{\mathbf{Z}}_{N0}^{-1} - \bar{\mathbf{I}}] = \bar{\mathbf{I}}_N, \quad (29)$$

where  $\bar{\Gamma}_n = \text{diag}(\Gamma_{nx}, \Gamma_{ny})$ . Since  $\bar{\Gamma}_n$  is a diagonal matrix, submitting it into (9) and using (27) yields:

$$\bar{\mathbf{Z}}_{N-1,N}^+ = \bar{\mathbf{I}} + \bar{\mathbf{z}}_{N-1,N}^+, \quad \bar{\mathbf{z}}_{N-1,N}^+ = j\beta_0 d_N \bar{\Delta}_N, \quad (30)$$

where  $\bar{\Delta}_n = \text{diag}(\mu_{ny} - \varepsilon_{nx}, \mu_{nx} - \varepsilon_{ny})$ . In deriving (30) we use the relations  $\bar{\mathbf{D}}_1 \bar{\mathbf{D}}_2 = \bar{\mathbf{D}}_2 \bar{\mathbf{D}}_1$ , if both  $\bar{\mathbf{D}}_1$  and  $\bar{\mathbf{D}}_2$  are diagonal, and  $[\bar{\mathbf{A}} + \bar{\mathbf{B}}]^{-1} \approx \bar{\mathbf{A}}^{-1} - \bar{\mathbf{A}}^{-1} \bar{\mathbf{B}} \bar{\mathbf{A}}^{-1}$ , if  $\|\bar{\mathbf{A}}\| \gg \|\bar{\mathbf{B}}\|$ . Using (10) and (28), we have,

$$\bar{\mathbf{Z}}_{N-1,N}^- = \bar{\mathbf{I}} + \bar{\mathbf{z}}_{N-1,N}^-, \quad (31)$$

where  $\bar{\mathbf{z}}_{N-1,N}^- = j\beta_0 d_N \bar{\mathbf{O}}_{N-1} \bar{\mathbf{O}}_N^T \bar{\Delta}_N \bar{\mathbf{O}}_N \bar{\mathbf{O}}_{N-1}^T$ .

Submitting (31) into (7) yields:

$$\bar{\mathbf{R}}_{N-1,N}^- \approx \bar{\Gamma}_{N-1} + [\bar{\mathbf{Z}}_{(N-1)0}^{-1} + \bar{\mathbf{I}}]^{-1} \bar{\mathbf{z}}_{N-1,N}^- \bar{\mathbf{Z}}_{(N-1)0}^{-1} [\bar{\mathbf{I}} - \bar{\Gamma}_{N-1}]. \quad (32)$$

Following the steps from (30) to (32) recursively with the form:

$$\bar{\mathbf{Z}}_{n,n+1}^- = \bar{\mathbf{I}} + \bar{\mathbf{z}}_{n,n+1}^-, \quad (33)$$

$$\bar{\mathbf{z}}_{n,n+1}^- = j\beta_0 \bar{\mathbf{O}}_n \left[ \sum_{m=n+1}^N d_m \bar{\mathbf{O}}_m^T \bar{\Delta}_m \bar{\mathbf{O}}_m \right] \bar{\mathbf{O}}_n^T. \quad (34)$$

Similar to the approximation to get (32), we have:

$$\bar{\mathbf{R}}_{n,n+1}^- \approx \bar{\Gamma}_n + [\bar{\mathbf{Z}}_{n0}^{-1} + \bar{\mathbf{I}}]^{-1} \bar{\mathbf{z}}_{n,n+1}^- \bar{\mathbf{Z}}_{n0}^{-1} [\bar{\mathbf{I}} - \bar{\Gamma}_n], \quad (35)$$

$$\bar{\mathbf{z}}_{n-1,n}^+ \approx \bar{\mathbf{I}} + j\beta_0 d_n \bar{\Delta}_n + \bar{\mathbf{z}}_{n,n+1}^- = \bar{\mathbf{I}} + \bar{\mathbf{z}}_{n-1,n}^+, \quad (36)$$

where

$$\bar{\mathbf{z}}_{n-1,n}^+ = j\beta_0 \bar{\mathbf{O}}_n \left[ \sum_{m=n}^N d_m \bar{\mathbf{O}}_m^T \bar{\Delta}_m \bar{\mathbf{O}}_m \right] \bar{\mathbf{O}}_n^T. \quad (37)$$

Submitting it to (10), we approximate  $\bar{\mathbf{Z}}_{n-1,n}^-$  to the form similar to (34). Finally, we have:

$$\bar{\mathbf{Z}}_{0,1}^- \approx \bar{\mathbf{I}} + j\beta_0 \sum_{n=1}^N d_n \bar{\mathbf{O}}_n^T \bar{\Delta}_n \bar{\mathbf{O}}_n, \quad (38)$$

and the total reflection coefficient,

$$\bar{\mathbf{R}} = \bar{\mathbf{R}}_{0,1}^- \approx \frac{j\beta_0}{2} \sum_{n=1}^N d_n \bar{\mathbf{O}}_n^T \bar{\Delta}_n \bar{\mathbf{O}}_n. \quad (39)$$

The low frequency limit of the total transmission coefficient is found in a similar way as:

$$\bar{\mathbf{T}} \approx \bar{\mathbf{I}} - \frac{j\beta_0}{2} \sum_{n=1}^N d_n \bar{\mathbf{O}}_n^T \bar{\mathbf{s}}_n \bar{\mathbf{O}}_n, \quad (40)$$

where  $\bar{\mathbf{s}}_n = \text{diag}(\mu_{ny} + \varepsilon_{nx}, \mu_{nx} + \varepsilon_{ny})$ .

Applying the low frequency limit of the reflection and transmission matrices for equivalent layer and multiple layers to (25) and (26), we have effective parameters as:

$$\theta_{et} = \frac{1}{2} \tan^{-1} \frac{\sum_{n=1}^N d_n (\varepsilon_{nx} - \varepsilon_{ny} + \mu_{nx} - \mu_{ny}) \sin 2\theta_n}{\sum_{n=1}^N d_n (\varepsilon_{nx} - \varepsilon_{ny} + \mu_{nx} - \mu_{ny}) \cos 2\theta_n}, \quad (41)$$

$$\theta_{er} = \frac{1}{2} \tan^{-1} \frac{\sum_{n=1}^N d_n (\varepsilon_{nx} - \varepsilon_{ny} - \mu_{nx} + \mu_{ny}) \sin 2\theta_n}{\sum_{n=1}^N d_n (\varepsilon_{nx} - \varepsilon_{ny} - \mu_{nx} + \mu_{ny}) \cos 2\theta_n},$$

$$\Delta_{xe,ye} = \frac{1}{2d_t} \sum_{n=1}^N d_n \left[ \Delta_{nx} + \Delta_{ny} \pm (\Delta_{nx} - \Delta_{ny}) \frac{\sin 2\theta_n}{\sin 2\theta_{er}} \right], \quad (42)$$

$$S_{xe,ye} = \frac{1}{2d_t} \sum_{n=1}^N d_n \left[ S_{nx} + S_{ny} \pm (S_{nx} - S_{ny}) \frac{\sin 2\theta_n}{\sin 2\theta_{er}} \right],$$

where  $d_t = \sum_{n=1}^N d_n$  and  $\mu, \varepsilon$  can be achieved by:

$$\mu_{pe} = \frac{S_{pe} + \Delta_{pe}}{2}, \quad \varepsilon_{pe} = \frac{S_{pe} - \Delta_{pe}}{2}. \quad (43)$$

Here, although there are two kinds of expressions for the effective angle, the relative difference between them is small and is about 1% in difference at frequency up to 10 GHz.

If we consider about non-magnetic materials or  $\mu$  is scalar, (41)-(43) can be simplified as:

$$\theta_e = \theta_{er} = \theta_{et} = \frac{1}{2} \tan^{-1} \frac{\sum_{n=1}^N d_n (\varepsilon_{nx} - \varepsilon_{ny}) \sin 2\theta_n}{\sum_{n=1}^N d_n (\varepsilon_{nx} - \varepsilon_{ny}) \cos 2\theta_n}, \quad (44)$$

$$\varepsilon_{xe,ye} = \frac{1}{2d_t} \sum_{n=1}^N d_n \left[ \varepsilon_{nx} + \varepsilon_{ny} \pm (\varepsilon_{nx} - \varepsilon_{ny}) \frac{\sin 2\theta_n}{\sin 2\theta_e} \right]. \quad (45)$$

If all layers are same but with different orientations, (41)-(43) can be further simplified as:

$$\theta_e = \theta_{er} = \theta_{et} = \frac{1}{2} \tan^{-1} \frac{\sum_{n=1}^N d_n \sin 2\theta_n}{\sum_{n=1}^N d_n \cos 2\theta_n}, \quad (46)$$

$$\varepsilon_{xe,ye} = \frac{1}{2} \left[ \varepsilon_x + \varepsilon_y \pm (\varepsilon_x - \varepsilon_y) \frac{\sum_{n=1}^N d_n \sin 2\theta_n}{d_t \sin 2\theta_e} \right], \quad (47)$$

$$\mu_{xe,ye} = \frac{1}{2} \left[ \mu_x + \mu_y \pm (\mu_x - \mu_y) \frac{\sum_{n=1}^N d_n \sin 2\theta_n}{d_t \sin 2\theta_e} \right],$$

which is the same as the result reported earlier in [7].

The z-component of the effective permittivity and permeability of the multilayered biaxial media can be found [6]:

$$\frac{1}{\varepsilon_{ze}} = \sum_{n=1}^N \frac{1}{\varepsilon_{nz}} \frac{d_n}{d_t}, \quad \frac{1}{\mu_{ze}} = \sum_{n=1}^N \frac{1}{\mu_{nz}} \frac{d_n}{d_t}. \quad (48)$$

### III. NUMERICAL RESULTS

In this section, we present numerical results showing the effective medium theory works well for multilayered anisotropic material with different orientations up to 10 GHz by comparing the parameters extracted without low frequency approximation with the ones with low frequency approximation.

The composite structure investigated is the four-layer non-magnetic medium. Figure 3 plots the real and imaginary parts of relative permittivity and permeability extracted from reflection and transmission coefficients with same thickness, same rotation angles and different relative permittivity (with same loss tangent in four layers) and permeability in x and y directions. Results

with and without the low frequency approximation are given. The frequency ranges from 10 MHz to 20 GHz. The real part of relative effective permeability is close to one (the relative permeability with low frequency limit is one in both x and y directions) and has nearly 1% difference at frequency up to 10 GHz. The effective permittivity also works up to 10 GHz. At low frequency range, the imaginary part of relative permeability is zero and imaginary part of relative permittivity is negative due to loss. When the frequency goes up, the relative permittivity and permeability would have imaginary parts with opposite signs, but the attenuation constant is still positive [11].

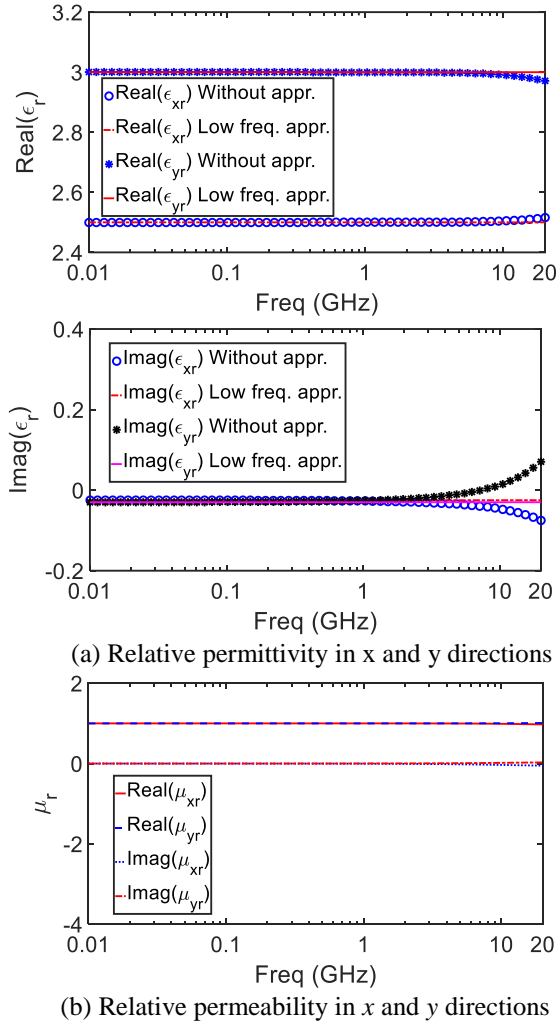


Fig. 3. Real and imaginary parts of relative permittivity and permeability of equivalent model with and without low frequency approximation for 4-layer biaxial non-magnetic media.  $d_{1,2,3,4} = 0.375$  mm,  $\epsilon_{x2,x4} = 3(1 - 0.01j)$ ,  $\epsilon_{y1,y3} = 4(1 - 0.01j)$ ,  $\epsilon_{x1,x3,y2,y4} = 2(1 - 0.01j)$ ,  $\theta_{1,2,3,4} = 30^\circ$ ,  $\theta_e = 30^\circ$ .

Figure 4 plots the real part of relative permittivity and permeability extracted from reflection and transmission coefficients with same thickness, different rotation angles and different relative permittivity and permeability in x and y directions. Again, there is a very good agreement for relative dielectric constants and effective angle between low frequency approximation and without it. The real part of relative effective permeability is almost one for frequency up to several GHz. Comparing without low frequency approximation the frequency independent model has a good agreement for frequency up to 10 GHz.

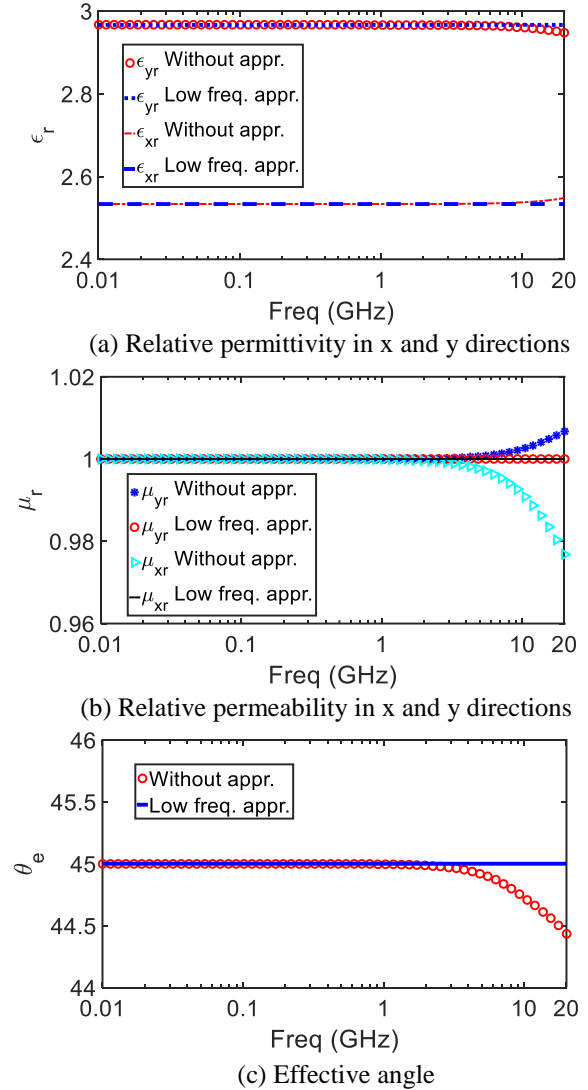


Fig. 4. Real part of relative permittivity and permeability of equivalent model with and without low frequency approximation for different 4-layer biaxial non-magnetic media.  $d_{1,2,3,4} = 0.375$  mm,  $\theta_{1,4} = 30^\circ$ ,  $\theta_{2,3} = 60^\circ$ ,  $\epsilon_{x2,x4} = 3$ ,  $\epsilon_{y1,y3} = 4$ ,  $\epsilon_{x1,x3,y2,y4} = 2$ .

#### IV. CONCLUSION

We have presented the method to model the multilayered biaxial anisotropic material with different orientation using effective medium theory. By using this method, multilayered biaxial anisotropic media with different orientations can be numerically regarded as an effective medium. A frequency independent model is derived using the low frequency approximation. Numerical examples show the good agreements for effective parameters between with and without low frequency approximation for the frequency up to 10 GHz.

#### ACKNOWLEDGMENT

This work is supported in part by the NSF IUCRC Program of the Center for Nondestructive Evaluation at Iowa State University and by the China Scholarship Council.

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