Four Speed Auto Transmission DC-DC Converter Control for E-Vehicle and Regenerative Braking Based on Simulation and Model Investigation

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Abstract

A novel single input multioutput (SIMO) output DC-DC converter with circular capacitors is intended to function with a single independent source to create numerous transmissions to regulate the speed at the same switching intervals. A novel single input multi output (SIMO) output DC-DC converter employing circular capacitors is designed to work with a single independent source to create numerous transmissions. The proposed converter generates 7 outputs in total, with 4 outputs generated simultaneously for forward operation (speed transmission) using the preferred source (fuel cell/battery) and 3 other different outputs used for regenerative transmissions, with the battery being the preferred storage device. This converter can control the speed of an electric vehicle (EV) by using the SIMO is output voltage to regulate the

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vehicle is speed, allowing for higher accelerations and decelerations with minimal energy loss and degradation of the main battery pack. It can also be used to power electronic components such as LED lights, audio systems, and mobile charging etc. The energy recovered during regenerative braking is used to charge the battery via a buck/boost operation for varied speed transmission. In addition, simulation, modelling, and analysis are used to validate the proposed system. It is intended for a fixed voltage of 12 V and output voltages ranging from 12 to 48 V. The PSIM simulation tool is used to validate the system. The validation demonstrates the suggested converter is good evidence in both braking and regenerative braking operations.

Keywords: Switched capacitor converter, DC-DC converter, single input multi output, E vehicle.

1 Introduction

In recent years, E vehicle (EV) plays a vital role in the means of transport in recent years. According to the international transport forum [8], due to rapid increase in urbanization the CO2 emissions will increase around 60% by 2050 which causes global warming. One of the main reasons for the introduction of EVs is the concern about greenhouse gas emissions and their contribution to the reduction of such harmful gas emissions. EVs have a lot of potential to reduce greenhouse gas emissions. There are two types of electric cars: plug–in hybrid electric vehicles (PHEV) and battery electric vehicles (BEV). The bat tery electric cars utilize energy to operate an electric motor and are powered by a battery pack. Similarly, with plugin hybrid electric cars, an internal combustion engine is utilized to power the vehicle in addition to the battery pack. An electric vehicle's fundamental components are a battery, a DC-DC converter, a power electronic controller, and a traction motor. Similarly in plug-in hybrid electric vehicles along with the battery pack, an internal combustion engine is also used to power the vehicle. The basic components of an EV are battery, DC-DC converter, a power electronic controller, and a motor for traction purpose. Similarly, smart vehicle are developed to overcome the conventional EV [13]. The smart vehicle are used with IOT based control, renewable [24] and nonrenewable based input sources to the EVs are currently used. Also, mechanical speed control are widely used and studied based on clutch control [16–18], automatic transmission control [6, 15], and gear shift control [17]. To make a efficient regenerative braking and speed transmission control, electrical

control will be preferred and fast. In this work, electrical based DC-DC speed control technique is used for controlling the speed of the E-vehicle. The DC-DC converter is used for controlling the speed of the EV and it is used for controlling other electronic devices in the EV system. For simplicity E-bike is considered for the discussion. For controlling the DC motor [5], DC-DC converter is required. Switched capacitor (SC) converter possess more advantages as compared to the conventional converters because the converter only uses switches and capacitors for the conversion operation, also these converters provides high efficiency and maximum target voltages but the inductor based converters [14] provides a good solution but have some limitations like EMI issues and iron losses. SC converters are widely used in many applications. High and medium power applications can also benefit from these switched capacitor DC–DC topologies [22]. For efficient conversion of DC to AC power, the output of such DC–DC converters is provided to DC–AC inverters to get AC voltage by regulating the inverter with relevant PWM methods [10–12]. Renewable energy sources are connected to the grid via high and medium power DC–DC converters. The general converter topology is considered i.e, single input multiple output (SIMO) switched-capacitor DC-DC converter is designed for speed transmission. In EV, battery is used for the acceleration of the vehicle using the DC-DC converter, i.e., it converts the fixed DC power from the battery to the variable DC which can be used by various part of the circuit and to drive the DC Motor in the vehicle. The SC converter is designed in such a way that, to maintain the voltage ripple and maintain the negative current [13] The main advantage of the proposed speed control system controls both acceleration/deceleration operation for both motoring and regenerative operation also used to control different electronic components in the vehicle.

1.1 Regenerative Braking

In an electrical vehicle, regenerative braking also helps to extend the vehicle's range. The kinetic energy is transformed to electrical energy during the regenerative braking cycle [23]. The driving range may be extended by using regenerative braking, which also increases braking efficiency. Many different types of study have been done on regenerative braking in the recent literature [7, 21, 23], but the four transmission system completely auto controller is not mentioned in many of them. A novel four-transmission system for forwarding and regenerative operation is explored in this paper. The suggested system's regenerative braking technology is shown in Figure [1.](#page-3-0)

Figure 1 Configuration of regenerative braking system.

2 Multi Output DC-DC Converter for Speed Transmission

Figure [2](#page-3-1) illustrates the proposed DC-DC converter. It's essentially a switched capacitor (SC) converter [19], with four capacitors and 14 switches linked in a circle with a single source as input $(V_{in}$ or V_{bat}) in the circuit's centre. Different output nodes can be used to link the numerous outputs $(V_{o1}-V_{o4})$ to the load. At each node, the output is connected across the output capacitor at the same time. Both step-up (acceleration) and step-down (deceleration) voltages are achievable with the proposed converter.

The voltage ratios that are obtained by this converter are (V_{bat}) , $(2V_{bat})$, $(3V_{bat})$, $(4V_{bat})$, $(0.5V_{bat})$ and $(0.33V_{bat})$. Table 1.1 shows the switching sequences for both forwarding and regenerative operation. The bidirectional switches are driven by two phases with a 50 % duty cycle ratio. The charging

Figure 2 Multi output DC-DC converter for Speed control.

Switches/Speed														
Transmission	S ₁	S_2	S_3	S_4	S_5	S_6	S_7	S_8	S_9	S_{10}	S_{11}	S_{12}	S_{13}	S_{14}
V_{bat}	P	N												
$2V_{bat}$			N	P	P	N	N							
$3V_{bat}$		$\overline{}$	N	P	P	N	$\overline{}$	P	P	N		N		
$4V_{bat}$			N	P	P	N	$\overline{}$	P	P	N	P	N	P	N
$1V_{bat}$	N	P												
$0.5V_{bat}$						N	1	$\overline{}$	N	P	N		N	P
$0.33V_{bat}$					N	P	N	$\overline{}$	N	P	N		N	P
$0.25V_{bat}$			P	N	N	P	N	$\overline{}$	N	P	N		N	P

Table 1 Acceleration and deceleration of speed transmission switching pattern

state is phase (ϕ_1), while the discharging condition is phase (ϕ_2). The output voltage ratios are produced by charging and discharging the flying capacitors in series and parallel combinations. The speed transmission or voltage ratios are given in Table 1.1 and the speed transmission switching details are also discussed. Here, the input voltage, V_{bat} is considered as 12 V. For the 1st transmission, the output voltage $V_{o1} = V_{bat} = 12$ V. Similarly, for the 4th transmission the output voltage $V_{o4} = 4V_{bat} = 48$ V. To generate the different speed transmission following switching sequence need to be considered. For simplicity $(3V_{bat})$ speed transmission is considered. Phase 1 involves charging the capacitors C_2 and C_3 in parallel with V_{bat} and turning on the switches S_4 , S_5 , S_7 and S_9 . Similarly, in phase 2, the capacitors C_2 and C_3 are linked in series with the voltage source and the negative terminal of the capacitor C_2 is connected to the voltage source, and the same capacitor is connected in series with C_3 through switches S_3 , S_6 , S_{10} , and S_{12} . The stored energy is given back to the battery via the proposed converter during regenerative braking. In Table [1,](#page-4-0) 'P' denotes a 50% positive half cycle, 'N' denotes a 50% negative half cycle, and '1' denotes a switch that is always ON.

2.1 Proposed Converter Loss Analysis

When building a SC converter [9], one of the most essential parameters to consider is equivalent resistance. For the sake of simplicity, voltage ratios of $(3V_{bat})$ are used in the analysis. Figures [3](#page-5-0) and [4](#page-5-1) depict the analogous circuit for the voltage ratio ($3V_{bat}$). The power loss [14] in any i^{th} operational phase is provided as,

$$
P_{R_{OUT_i}} = I_o^2 R_{OUT_i} \tag{1}
$$

Assume that all switch resistances are the same and that parasitic effects (ESR) for all flying capacitors are the same. In addition, as compared to

Figure 3 Proposed equivalent circuit of charging state $(3V_{bat})$.

Figure 4 Proposed Equivalent Circuit of Discharging state $(3V_{bat})$.

the flying capacitor capacitance $(C_{01}, C_{02}, C_{03}, C_{04})$, the filter capacitor capacitance (C_1, C_2, C_3, C_4) is high. The current equation is given in [\(2\)](#page-5-2)–[\(4\)](#page-5-3) using the technique outlined in [3], the charge balance equation, and nodal KCL analysis for phases ϕ_1 and ϕ_2 as shown below,

$$
I_1 = I_2 + I_3 \t\t(2)
$$

$$
I_4 = I_1 \tag{3}
$$

$$
I_4 = I_1 = I_0 \tag{4}
$$

The capacitor charging and discharging equation is obtained from Fig-ures [3](#page-5-0) and [4](#page-5-1) and is given in $(5)-(8)$ $(5)-(8)$ $(5)-(8)$.

$$
R_C = \frac{1}{2}R_{on} + \frac{1}{2}ESR\tag{5}
$$

$$
C_C = 2C\tag{6}
$$

$$
R_T = 4R_{on} + 2ESR\tag{7}
$$

$$
C_T = \frac{C}{2} \tag{8}
$$

Model	Simulated
$R_{eq}(\Omega)$	$R_{eq}(\Omega)$
4.16	4.13
4.16	4.14
5.20	5.18
6.94	6.93

Table 2 Equivalent resistance of four speed transmission

Table 3 Comparison results of V_{rat} , V_{om} and V_o speed transmission

Frequency	Voltage	Model	Analysis	Simulated
kHz.	Ratios	V_{rat} (V)	$V_{\alpha m}$ (V)	V _o
100	V_{bat}	11.99	11.95	11.95
100	$2V_{bat}$	23.99	23.94	23.94
100	$3V_{bat}$	35.98	35.95	35.95
100	$4V_{bat}$	47.98	47.93	47.93

The R_{eq} [14] is calculated by combining [\(5\)](#page-5-4), [\(6\)](#page-5-6), [\(7\)](#page-5-7), and [\(8\)](#page-5-5) and it is given by,

$$
R_{eq} = \phi_C^2 \frac{1}{2f_s C_C} \coth\left(\frac{\lambda_C}{2}\right) + \phi_T^2 \frac{1}{2f_s C_T} \coth\left(\frac{\lambda_T}{2}\right) \tag{9}
$$

Similar steps are followed for solving R_{eq} for other voltage ratios. The *R*_{eq} of other voltage ratios is given in Table [2](#page-6-0) [25].

3 Simulation and Case Study of Proposed Converter

In this work, only electrical speed transmission control is designed using existing mechanical braking systems [7, 18, 21]. The proposed converter is simulated using PSIM tool and it is validated using the model which is designed using bidirectional switch and the parameters of the MAX4678 switches $S_1 - S_{14}$ are $R_{on} = 0.4\Omega$ [20] referring to the Figure [2.](#page-3-1) The load current varies from 2 mA to 1 A at a voltage of 12 V for the different voltage ratios, and the flying capacitor and output capacitor are rated at 22μ F with an ESR of 100 m Ω , 220 μ F with a load resistance of 5 k Ω , and the load current ranges from 2 mA to 1 A at a voltage of 12 V. The comparative findings of the model (V_m), simulated (V_{out}), and theoretical voltages (V_o) of the 3 V_{in} ratio are shown in Table [3.](#page-5-0) The simulations are carried out under the following scenarios.

Case 1: Proposed converter outputs (V_{o1} to V_{o4}) is connected to elec tronic loads.

Case 2: One of the output is connected to EV (Motor Load) and the remaining outputs are connected to electronics load.

Case 3: Regenerative voltage fed back to the V_{bat} .

i. Case 1

In this scenario, the electronic load is linked to all of the proposed converter's loads. The output voltage and voltage ripple of the $3V_{bat}$ voltage ratio is shown in Figure [5,](#page-7-0) with a voltage ripple of 0.1 V. All of the simulated output voltages are almost identical to the model values, as shown in Figure [6.](#page-8-0) The simulated output voltage of $3V_{bat}$ is 35.97 V, as shown in Figure [7,](#page-8-1) and it is evident that the simulated output voltage is nearly similar to the model voltages. In addition, the load variation for the suggested converter is shown in Figure [5](#page-7-0) by altering the resistance value from 5 kΩ to 1 kΩ for the voltage ratio $3V_{bat}$. By comparing the findings of (V_o) , (V_m) and (V_{out}) values that are in excellent agreement with each other, the suggested converter is concluded.

Figure 5 Load variation of $(3V_{bat})$.

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Figure 6 Comparison of speed transmission voltage with model voltage.

Figure 7 Simulation of proposed converter output voltage for $3V_{bat}$ mode.

ii. Case 2

The parameters of torque, speed, and the current are assumed using t_p and f_w . Assumption are made for designing the E vehicle parameters. The parameters are motor/gear is 3 kg, controller is 0.5 kg, battery 3 kg and the cyclist is 10 kg. Let us considered the real time parameter of a bicycle where the speed, V_b is 5 km/hr, F_d is 13 Nm, P_d is 18 W, head wind speed is 1 km/hr and adding 2 W power to propel then P_d is 20 W. When designing the EV, realtime factors are taken into account. Assume the EV's power and torque is constant. Figure 8 depicts the proposed converter's simulated output voltage when the load is connected to the motor. It provides the efficient results of

Figure 8a Simulated output voltages of E-vehicle when motor load is connected at output terminal.

Figure 8b Parameter design using Bicycle model.

output voltage 11.98 V, load current 1.68 A, torque is 13 Nm, input voltage is 12 V, speed is 13.6 RPM. From this, it is clear that even motor load is connected to the proposed converter it provides efficient operation.

iii. Case 3

The energy from the EV is supplied back to the source during regenerative braking using the same suggested converter, which will serve as a buck operation for charging the battery utilizing different step down voltage ratios. For the sake of simplicity, regenerative operation is assumed to be $(0.3V_{\text{out}})$, and the pulse pattern is shown in Table [1.](#page-4-0) If the regeneration voltage is less than the source voltage (i.e., the battery voltage), the proposed converter would charge the battery as a boost operation. When regenerative braking is operational, Figure [9](#page-9-0) displays the simulated output voltage of the proposed converter. Figure [10](#page-11-0) depicts the total efficiency of the proposed converter for both forwarding and regenerative operation. Table [4](#page-11-1) shows the overall comparison of different factors with previous research studies. As a result, the suggested converter has a higher efficiency, fewer switches and capacitors, and lower voltage ripple. In addition, the suggested converter would operate in both forwarding and regenerative modes without requiring any changes to the circuit architecture. In this simulation, switched capacitor converter provides high efficiency [20] in open loop conditions as shown in the Figure [10.](#page-11-0)

Figure 9 Simulated output voltage of regenerative braking [25].

Figure 10 Efficiency of Proposed Converter [25].

	No of	No of	No of	No of		Voltage
Authors	Switches	Inputs	Outputs	Capacitors	Regenerative	Ratios
$\lceil 1 \rceil$				2 (with inductors)	No	
$\lceil 2 \rceil$		4	3	3 (with inductors)	No	
[4]					No	2
This work	14				Yes	10

Table 4 Comparison results with other switched capacitor speed controller converter [25]

So the closed loop system is not necessary for the proposed system for manual transmission. To make more efficient and speedy operation closed loop operation may be considered for automatic switching in Case 3. Furthermore, loading and unloading are left for further studies. The comparison results of proposed topology with other switched capacitor speed controller converter is shown in Table [4.](#page-11-1)

4 Conclusions

The proposed speed transmission system provides the speed control in E-Vehicle (EV) for higher accelerations and deceleration. The transmission control is also used to control regenerative braking, which uses slowdown or acceleration to feed energy back into the battery. In addition, simulation, modelling, and analysis are used to ensure that the proposed system delivers optimum efficiency and effective braking actions. The four transmission speed control is designed using 14 switches and 4 capacitors. The efficiency of the proposed system is more than 90% when the bicycle load is considered and the speed is 13 RPM and the measured torque is 15 Nm. In addition, this proposed converter can be used both in fuel cell and the battery systems. The main advantage of this system is multiple speed transmission (1, 2, 3 times of the input voltage) is possible by performing different charging operation of the capacitors in different switching pattern.

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