Journal of Mobile Multimedia, Vol. 1, No.1&2 (2015) 157-176 © Rinton Press

FUZZY, NEURAL NETWORK AND EXPERT SYSTEMS METHODOLOGIES AND APPLICATIONS-A REVIEW

ROOH UL AMIN LI AIJUN

School of Automation

Northwestern Polytechnical University, Xi'an, China. rooh@mail.nwpu.edu.cn

MALIK MAZHAR ALI

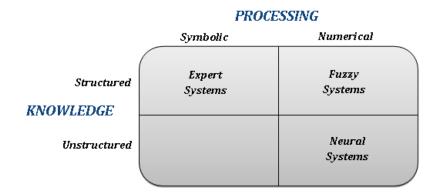
Department of Physics Allama Iqbal Open University, Islamabad, Pakistan.

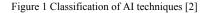
The rapid growth in the field of artificial intelligence from past one decade has a significant impact on various application areas i.e. health, security, home appliances among many. In this paper we aim to review artificial intelligence methodologies and their potential applications intended for variable purposes i.e. Agriculture, applied sciences, business, engineering, finance, management etc. For this purpose articles from past one decade (from 2004 to 2013) are reviewed in order to explore the most recent research advancements in this domain. The review includes 172 articles gathered from related sources including conference proceedings and academic journals. We have categorized the selected articles into four main categories i.e. fuzzy systems, neural network based systems, neuro fuzzy systems and expert systems. Furthermore, expert systems are further classified into three categories: (i) rule based expert systems, (ii) knowledge based expert systems and (iii) intelligent agents. This review presents research implications for practitioners regarding integration of artificial intelligence techniques with classical approaches and suggestions for exploration of AI techniques in variable applications.

Key words: Literature survey, Artificial intelligence methodologies, Fuzzy systems, Neural network, Expert systems

1 Introduction

Over the past few decades, Artificial intelligence (AI) techniques have been extensively used in various fields and have replaced classical techniques by incorporating intelligent behavior of user to solve complex and challenging problems [1]. The basic idea behind AI techniques is the perfect embodiment of the blend of human experience, task-specific knowledge and computational intelligence and processing. AI techniques can be categorized in two ways such as: according to the form of the knowledge (either structured or unstructured); and the way in which this knowledge is processed (either symbolic or numerical) as shown in Figure 1.





AI techniques provide correctness, robustness, extendibility and reusability for solution of various problems where conventional methods have proven insufficient[2]. Hence rapid growth in the use of AI techniques has been observed in many areas of science, engineering, industry and societal processes. Though modern AI was formally introduced in 1956 but the last decade has witnessed so many important advancements and innovations in artificial intelligence at a rapid pace that have had a significance impact on almost all application areas. Reasons for this phenomenon are threefold:

- 1. Correctness and robustness offered by AI methodologies
- 2. Increase in computational power and application area
- 3. Gradual increase in access to online technical resource

This paper surveys AI techniques (fuzzy, neural network and expert systems methodologies) and applications, developed in the last decade to explore application areas of each methodology and draw implications for future research and development. The survey can be regarded as an extension of the previous work done in the AI domain [3], [4]. Since that survey was for the period 1995-2004 and it included all expert systems techniques however some of them are now being used in combination of other techniques so there was need for an updated survey with techniques used in almost every application area

This review survey is based on articles from 2004 to 2013. The retrieved articles were searched in electronic resources like Elsevier, Emerald, EBSCO, IEEE Xplore, Wiley online databases as well as several online journals and conference proceedings. Initially more than 1000 articles relevant to the topic were scanned, later only 172 were selected based on their relevancy with the research theme and novelty of ideas and implementation. This paper surveys four methodologies of AI techniques based on [2]: fuzzy systems, neural network based systems, neuro fuzzy systems and expert systems, along with their application for different research domains. Besides fuzzy and neural network based systems, object-oriented methodology, case-based reasoning, system architecture development, intelligent agent systems, modeling, ontology and database management but only rule based expert systems, knowledge

based expert systems and intelligent agents are considered in this survey. The reason is that major contribution in expert systems during the last decade falls in selected categories.

The rest of the paper is structured as follows: Sections 2-5 present survey results of fuzzy, neural and expert system methodologies and their applications. Section 6 contains research trends and future development in these AI techniques. In last section, concise conclusion is presented.

2 Fuzzy Systems and their Applications

Fuzzy system uses fuzzy logic, introduced by Zadeh in [5]. Since its introduction, fuzzy systems have had successful applications in many diverse fields for solution of generic and specific problems. Conventionally decision making in computers was rigid (yes-no, true-false, 0-1). On the contrary, fuzzy systems provide flexibility in decision making through incorporation of fuzzy sets and rules (allow graduation from true to false, yes to no and 0 to 1). This kind of decision making enables computers to imitate human reasoning. The technique is applied in situations where decision or conclusion is not matter of yes or no (true or false, 0 or 1) and often involve several degrees between yes and no.

Some of applications implemented by fuzzy based systems are such as fault diagnosis in electric systems, medical diagnosis/treatment, nonlinear system control, software engineering, unmanned air vehicles control, wastewater management, decision making, fuzzy control system design, mobile robot navigation, object tracking, pattern recognition, robot kinematic solution, robot manipulator control, supply chain management, twin rotor system control, fault detection, intrusion detection, risk management, flood frequency analysis and stock forecast. The methodologies of fuzzy based systems along with their applications are listed in Table 1.

Fuzzy systems/applications	Authors
Fault diagnosis in electric systems	[6], [7]
Medical diagnosis/treatment	[8], [9], [10]
Nonlinear system control	[11], [12]
Software engineering	[13], [14]
Unmanned air vehicles	[15], [17]
Wastewater management	[16], [17]
Decision making	[18], [19]
Fuzzy control system design	[20], [21]
Mobile robot navigation	[22], [23]
Object tracking	[24], [25]
Pattern recognition	[26], [27]
Robot kinematic solution	[28], [29]
Robot manipulator	[30], [31]
Supply chain management	[32], [33]
Twin rotor system	[34][35]
Fault detection	[36]
Intrusion detection	[37]
Risk management	[38], [39]
Flood frequency analysis	[40], [41]
Stock forecast	[42], [43]

Table 1Fuzzy systems and applications

3 Neural Networks based Systems and their Applications

Artificial neural network (ANN) is a computational model that emulates biological neurons. ANN was proposed in the 1940s but due to technical limitations could not be implemented until the 1980s. ANNs are made up of parallel layers of nodes (neurons) which are interconnected with varying weights (synaptic weights) [2]. The nodes receive input that are analogous to the electrochemical impulses that dendrites of biological neurons receive from one-another. The output of node is analogous to signal sent out from neuron over its axon. Various network architectures have been proposed according to nature of applications. ANN has distributed architecture which is extremely suitable for parallel processing and it has ability to learn on-line as compare to other methodologies [2].

The applications using neural network based systems include fault diagnosis, industrial and process control, robot kinematic solution/control, support vector machine learning, EEG signal classification/detection, nonlinear system control, pattern recognition, medical diagnosis/treatment, agriculture, exchange rate forecasting, object recognition, software project management, industrial PID controller, mobile robot navigation, robot manipulator control, unmanned air vehicles control and twin rotor system control. The methodologies of neural network based systems along with their applications are listed below in Table 2.

Neural Network based systems/applications	Authors
Fault diagnosis	[44], [45]
Industrial and process control	[46], [47]
Robot kinematic solution/control	[48], [49]
Support vector machine learning	[50], [51]
EEG signal classification/detection	[52], [53]
Nonlinear system control	[54]
Pattern recognition	[55], [56]
Medical diagnosis/treatment	[57], [58]
Agriculture	[59]
Exchange rate forecasting	[60], [61]
Object recognition	[62], [63]
Software project management	[64], [65]
Industrial PID controller	[66], [67]
Mobile robot navigation	[68], [69]
Robot manipulator	[70], [71]
Unmanned air vehicles	[72], [73]
Twin rotor system	[74]
Computer Games	[75], [76]

Table 2Neural Network based systems and applications

4 Neuro Fuzzy Systems and their Applications

Fuzzy systems proved effective in dealing with problems that cannot be solved through conventional approaches. However there are several applications for which extraction of suitable collection of fuzzy rules from available data set is still a challenge i.e. fuzzy membership function type and fuzzy rules are

determined using trial and error by users [2]. Researchers have so far tackled this problem by designing fuzzy systems with combination of neural network (e.g. [77]). Because the neural network learning algorithms can be used to identify the parameters of fuzzy systems, the resulting neuro-fuzzy system offers the strength of both methodologies while overcoming some of the limitations of individual techniques.

Some of application areas based on neuro fuzzy systems are hydrology, intrusion detection, nonlinear system control, pattern recognition, EEG signal classification, object recognition, robot manipulator control, mobile robot navigation, medical diagnosis/treatment, fault diagnosis, induction motor control, software engineering, agriculture, inverted pendulum systems, stock market, HVAC, Twin rotor system control, wastewater management, CMOS circuits modelling & simulation, unmanned air vehicles and robot kinematic solution/control. The methodologies of neuro fuzzy systems along with their applications are listed below in Table 3.

Neuro Fuzzy systems/ applications	Authors			
Hydrology	[78], [79]			
Intrusion detection	[80], [81]			
Nonlinear system control	[82], [83]			
Pattern recognition	[84], [85]			
EEG signal classification	[86], [87]			
Object recognition	[88], [89]			
Robot manipulator	[90], [91]			
Mobile robot navigation	[92], [93]			
Medical diagnosis/treatment	[94]			
Fault diagnosis	[95], [96]			
Induction motor control	[97], [98]			
Software engineering	[99], [100]			
Agriculture	[101]			
Inverted pendulum systems	[102], [103]			
Stock market	[104], [105]			
HVAC	[106]			
Twin rotor system	[107], [108]			
Wastewater management	[109], [110]			
CMOS circuits modeling & simulation	[111]			
Unmanned air vehicles	[112]			
Robot kinematic solution/control	[113], [114]			

Table 3 Neuro fuzzy systems and applications

5 Expert Systems and their Applications

Expert systems are programming methodologies, designed to emulate human expert skills by making extensive use of specialized knowledge to solve problems [2]. The term emulate is used in sense that expert systems are intended to act like human experts in all respects. Expert systems can also be defined as combination of knowledge and inference. Experts systems offer advantages of fast response, intelligent data base, increased availability and performance and reduced cost and danger. From half of a century, experts systems have been successfully employed in business, medicine, economics, science and engineering. The three main categories of expert systems are

- 1. Rule-based expert systems
- 2. Knowledge-based expert systems
- 3. Intelligent agents

5.1. Rule-based Expert Systems

Rule-based expert system is defined as an automated system which contains information as an encoded human expert's knowledge. The information consists of a set of IF (condition)-THEN (action) rules, a set of facts and some interpreter, providing given facts, controlling the implementation of the rules [115]. The rules are applied on some data for inference of results to reach a suitable conclusion. Computer software or routines are used as inference mechanism in order to deduce rational results from set of rules and facts and formulate conclusion.

Rule-based expert systems and applications Rule-based expert systems/applications Authors				
Rule-based expert systems/applications				
Distribution planning	[116]			
Geosciences	[117]			
Knowledge representation	[118]			
Sensor control	[119]			
Tutoring system	[120]			
Haptic devices modelling	[121]			
Knowledge acquisition	[122]			
Medical treatment	[123], [124]			
Fault diagnosis	[125], [126]			
Topological observation	[127]			
Intrusion detection system	[128]			
Online learning system	[129]			
Pipeline leak detection	[130]			
Translation	[131], [132]			
Maritime surveillance	[133]			
Project scheduling	[134]			
Chemical reactions	[135]			
Agriculture	[136]			
Electrical distribution	[137]			
Oil fields	[138]			
Algebraic problem solving	[139]			

Table 4 Rule based expert systems and applications

Some of application areas using rule-based expert systems are geosciences, sensor control, distribution planning, tutoring system, knowledge representation, haptic devices modelling, knowledge acquisition, medical treatment, topological observation, fault diagnosis, online learning system, intrusion detection system, translation, pipeline leak detection, maritime surveillance, project scheduling, chemical reactions, electrical distribution, agriculture, oil fields and algebraic problem solving. Rule-based expert systems methodologies and their applications are summarized in Table 4.

5.2. Knowledge-based Expert Systems

Knowledge based expert systems (KBS) are computer software that use a knowledge base to solve problems in different complex environments. KBS are different as compare to conventional computer software in a manner that knowledge is encoded explicitly via tool rather than implicitly via code. The essential components of KBS are user interface, inference engine and knowledge base. The user supplies some information or facts to KBS and receives expertise in response. The inference engines use the knowledge encoded in knowledge base to draw conclusions. The knowledge base is required to grow and change as knowledge is added. Today, a wide range of knowledge-based expert systems have been built and successfully deployed.

Some application areas employing knowledge-based expert systems are robotics, strategic planning, building architecture design, defence budget planning, supply chain system, fault diagnosis, medical treatment, agricultural management, performance evaluation, stock trading, bioinformatics, decision support, image processing, process Industries, molecular biology, risk management and storm water management. Knowledge-based expert systems and their applications are listed in Table 5.

Knowledge-based expert systems/applications	d applications Authors		
Robotics	[140], [141]		
Strategic planning	[142]		
Building architecture design	[143]		
Defence budget planning	[144]		
Supply chain system	[145]		
Fault diagnosis	[146], [147]		
Medical treatment	[148],[149]		
Agricultural management	[150]		
Performance evaluation	[151]		
Stock trading	[152]		
Bioinformatics	[153]		
Decision support	[154], [155]		
Image processing	[156], [157]		
Process Industries	[158]		
Molecular biology	[159]		
Risk management	[160]		
Storm water management	[161]		

Table 5 Knowledge-based expert systems and applications

5.3. Intelligent Agents

Intelligent agents are computer software routines and are also named as wizards, software agents and multi-agents (turban). An intelligent agent is computer software that is capable of flexible autonomous action in a defined environment in order to meet its design objectives [162]. Intelligent agents are reactive (able to perceive their environment and respond in a timely manner), pro-active (able to exhibit goal-directed behavior by taking the initiative) and social-able (able to interact with other agents or humans) in order to satisfy their design objectives.

Some of application based on intelligent agents are agricultural decision support, building architecture design, knowledge representation and management, stock prediction system, supply chain system, decision support, system analysis and design, anti-money laundering, tutoring system, webbased education system, adaptive learning system and power grid control. Intelligent agents based systems and their applications are summarized in Table 6.

Intelligent agents/applications	Authors
Agricultural decision support	[163]
Building architecture design	[164]
Knowledge representation and management	[165]
Stock prediction system	[166]
Supply chain system	[167], [168]
Decision support	[169]
System analysis and design	[170], [171]
Anti-money laundering	[172]
Tutoring system	[173], [174]
Web-based education system	[175]
Adaptive learning system	[176]
Power grid control	[177]

Table 6 Intelligent agents and applications

6 Discussion

Fuzzy, neural and expert systems have diverse applications in today's world. The comprehensive research domain finds its applications in almost every field. The aim of this review was to explore the diverse applications of the aforementioned techniques and presenting some suggestions for improvement in existing solutions. The methods and their respective applications presented in this review do not cover all of the fields yet the most cited and applied work in this domain is selected for review. The applications are classified according to the problem domain.

In this review, we have covered the application domains of the neural, fuzzy and expert systems techniques such as agriculture, aerospace, biochemistry, bioinformatics, biomedical, biology, chemistry, computer science, education, economics, energy engineering, hydrology, health care, HVAC, image processing, metallurgy, mathematics, mechanical, medical, management sciences, oil fields, power systems, robotics and water resources. A Comparison among some application area is given in Table 7.

Application Ares	Fuzzy	Neural	Neuro	Rule	KB ES	Intelligent
	-		Fuzzy	based ES		agents
Agriculture		\checkmark	\checkmark	\checkmark		
Control system design		\checkmark	\checkmark			
Decision making		\checkmark	\checkmark	\checkmark	\checkmark	\checkmark
Fault diagnosis		\checkmark	\checkmark	\checkmark	\checkmark	\checkmark
Flight Control		\checkmark	\checkmark			
Flood frequency analysis		\checkmark	\checkmark			
Image Processing		\checkmark	\checkmark		\checkmark	\checkmark
Intrusion detection		\checkmark	\checkmark	\checkmark	\checkmark	\checkmark
Medical Sciences		\checkmark	\checkmark	\checkmark	\checkmark	\checkmark
Nonlinear Control		\checkmark	\checkmark			
Risk management		\checkmark	\checkmark	\checkmark	\checkmark	
Robotics		\checkmark	\checkmark	\checkmark	\checkmark	
Software engineering		\checkmark	\checkmark	\checkmark	\checkmark	\checkmark
Stock forecast		\checkmark	\checkmark	\checkmark	\checkmark	\checkmark
Supply chain		\checkmark	\checkmark			\checkmark
management						

Table 7 Comparison of Application areas

In the above table, empty fields shows that particular methodology is rarely or never used in the corresponding application area. It is clear that applications in several domains i.e. robotics, image processing, fault diagnosis have employed several methodologies to provide solutions e.g. for a problem of unmanned air vehicles control fuzzy control, neural network control and neuro fuzzy control are implemented, yet not implemented in knowledge based expert systems and rule based expert systems. This shows that each of the methodologies has its own limitations and suitability criteria that make one methodology not suitable for all applications. Moreover, it can be analyzed from the review results that the authors use problem solving techniques based on their academic background and expertise. For instance fault diagnosis has been done almost with every technique. This shows that several problems can be solved with multiple techniques and the preference factors can be many including problem solvers' expertise and knowledge of the area.

The review revealed that some of the methodologies share common concepts and thus have been used in combination for several applications. For instance fuzzy systems, rule based expert systems and knowledge based expert systems have similar concepts in contrast to neural network based systems. However despite of similarity in concepts, some applications are not yet capable to be handled by these similar techniques. This shows that the selection of technique for problem solution depends on other factors than the suitability of technique including problem solving technique's viability. For example fuzzy, neural and neuro fuzzy techniques are widely used for nonlinear system control but rule based expert systems and intelligent agents techniques have rarely used for this domain because these techniques are not viable. Therefore the review results unfold that in order to find solution of a problem with the help of AI techniques requires some problem solver's expertise, his/her background knowledge of the application domain and of that methodology, and the technique's viability for the domain.

7 Limitations

This survey is intended to summarize the advances made in fuzzy, neural network and expert systems methodologies and applications for the last one decade. Several limitations of this work are discussed below.

The basic limitation of any review is the bias in the selection of studies and the possible imprecision in data extraction from the variable sources. The categorization with respect to methodologies and their respective application area was an intricate task so in that context, it might have been possible that some of the potential studies were missed which might have been included to draw more conclusions.

Furthermore keyword index was used for search, so any published work without these keywords might have been missed regardless of its relevance with the topic.

Another, limitation in this domain was the language of publications. This survey has not included articles from non-English resources due to researchers' lack of comprehension of other languages. It has been come across during the extensive study search that huge amount of work done in this domain is published in other languages (such as Chinese mandarin, German and Russian). Therefore, including the studies published in English language only has limited the scope of this study

8 Suggestions & Implications

Some suggestions and implications are presented here.

Integration of different AI techniques. Artificial intelligence is a broad field and several techniques have been developed so far for various problems and research domains. Therefore it is essential for development of new AI techniques that different techniques must be integrated for different research domains. It will widen the domain of AI techniques as well as many challenging problem shall be solved.

Fusion of AI techniques with classical approaches. In study of some applications it is found that enhanced performance was obtained when these techniques were fused with classical techniques. For example neural network based sliding mode control (nonlinear control technique) of robotic manipulator is more efficient than neural network control of robotic manipulator.

Adaption of Innovation. Innovation is a key of technological evolution. For the development of AI techniques it necessary to learn and share, apply new ideas in different fields, adapt new problem solving techniques and make use of advancement in a technique in diverse applications.

9 Conclusion

This paper reviews the applications of AI techniques i.e. fuzzy, neural and expert systems methodologies for the last one decade (2004-2013). The survey is based on the articles selected from various online databases, conference proceedings and literature studies. The aforementioned AI methodologies are classified with respect to their research and applications domains. The review revealed that the AI techniques have found their applications in diverse field including health, agriculture, home appliances, and education among many. It is concluded that problem solving using a

specific technique depends upon expertise and background knowledge of the problem solver, and viability of the technique. This proves that not every technique is suitable for solving multiple problems. Moreover, it is also suggested that fusion of AI techniques with classical approach may result in a broader research domain and widen application domain of these techniques. Finally innovation is essential for evolution of these techniques and has been the key for the development so far.

References

- [1] B. Coppin, Artificial Intelligence Illuminated. 2004, p. 768.
- [2] R. E. King, *Computational Intelligence in Control Engineering*. Marcel Dekker, Inc. New York, 1999.
- [3] S. Liao, "Expert system methodologies and applications—a decade review from 1995 to 2004," *Expert Syst. Appl.*, vol. 28, no. 1, pp. 93–103, Jan. 2005.
- [4] S. Sahin, M. R. Tolun, and R. Hassanpour, "Hybrid expert systems: A survey of current approaches and applications," *Expert Syst. Appl.*, vol. 39, no. 4, pp. 4609–4617, Mar. 2012.
- [5] L. A. Zadeh, "Fuzzy sets," Information and Control, vol. 8. pp. 338–353, 1965.
- [6] J. Sun, S. Qin, and Y.-H. Song, "Fault Diagnosis of Electric Power Systems Based on Fuzzy Petri Nets," *IEEE Trans. Power Syst.*, vol. 19, pp. 2053–2059, 2004.
- [7] R. Isermann, "Model-based fault-detection and diagnosis Status and applications," Annual Reviews in Control, vol. 29. pp. 71–85, 2005.
- [8] P. R. Innocent and R. I. John, "Computer aided fuzzy medical diagnosis," *Inf. Sci. (Ny).*, vol. 162, pp. 81–104, 2004.
- [9] R. I. John and P. R. Innocent, "Modeling uncertainty in clinical diagnosis using fuzzy logic.," *IEEE Trans. Syst. Man. Cybern. B. Cybern.*, vol. 35, pp. 1340–1350, 2005.
- [10] R. Seising, "From vagueness in medical thought to the foundations of fuzzy reasoning in medical diagnosis," *Artif. Intell. Med.*, vol. 38, pp. 237–256, 2006.
- [11] S. Labiod and T. M. Guerra, "Adaptive fuzzy control of a class of SISO nonaffine nonlinear systems," *Fuzzy Sets Syst.*, vol. 158, pp. 1126–1137, 2007.
- [12] A. Boulkroune, M. Tadjine, M. M'Saad, and M. Farza, "Fuzzy adaptive controller for MIMO nonlinear systems with known and unknown control direction," *Fuzzy Sets Syst.*, vol. 161, pp. 797–820, 2010.
- [13] Z. Xu and T. M. Khoshgoftaar, "Identification of fuzzy models of software cost estimation," *Fuzzy Sets Syst.*, vol. 145, pp. 141–163, 2004.
- [14] J. Aroba, J. J. Cuadrado-Gallego, M.-A. Sicilia, I. Ramos, and E. García-Barriocanal, "Segmented software cost estimation models based on fuzzy clustering," *Journal of Systems and Software*, vol. 81. pp. 1944–1950, 2008.
- [15] L. Doitsidis, K. P. Valavanis, N. C. Tsourveloudis, and M. Kontitsis, "A framework for fuzzy logic based UAV navigation and control," *IEEE Int. Conf. Robot. Autom. 2004. Proceedings. ICRA* '04. 2004, vol. 4, 2004.
- [16] E. F. Carrasco, J. Rodriguez, A. Punal, E. Roca, and J. M. Lema, "Diagnosis of acidification states in an anaerobic wastewater treatment plant using a fuzzy-based expert system," *Control Eng. Pract.*, vol. 12, pp. 59–64, 2004.
- [17] M. Fiter, D. Güell, J. Comas, J. Colprim, M. Poch, and I. Rodríguez-Rodal, "Energy saving in a wastewater treatment process: an application of fuzzy logic control.," *Environ. Technol.*, vol. 26, pp. 1263–1270, 2005.
- [18] J. Ye, "Fuzzy decision-making method based on the weighted correlation coefficient under intuitionistic fuzzy environment," *Eur. J. Oper. Res.*, vol. 205, pp. 202–204, 2010.

- 168 Fuzzy, Neural Network and Expert Systems Methodologies and Applications: A Review
- [19] G. Wei, "Hesitant fuzzy prioritized operators and their application to multiple attribute decision making," *Knowledge-Based Syst.*, vol. 31, pp. 176–182, 2012.
- [20] A. Sala, T. Guerra, and R. Babuska, "Perspectives of fuzzy systems and control," *Fuzzy Sets Syst.*, vol. 156, pp. 432–444, 2005.
- [21] B.-J. Rhee and S. Won, "A new fuzzy Lyapunov function approach for a Takagi–Sugeno fuzzy control system design," *Fuzzy Sets and Systems*, vol. 157. pp. 1211–1228, 2006.
- [22] X. Yang, M. Moallem, and R. V. Patel, "A layered goal-oriented fuzzy motion planning strategy for mobile robot navigation," *IEEE Trans. Syst. Man, Cybern. Part B Cybern.*, vol. 35, pp. 1214–1224, 2005.
- [23] M. A. P. Garcia, O. Montiel, O. Castillo, R. Sepúlveda, and P. Melin, "Path planning for autonomous mobile robot navigation with ant colony optimization and fuzzy cost function evaluation," *Applied Soft Computing*, vol. 9. pp. 1102–1110, 2009.
- [24] J. Figueroa, J. Posada, J. Soriano, M. Melgarejo, and S. Rojas, "A Type-2 Fuzzy Controller for Tracking Mobile Objects in the Context of Robotic Soccer Games," 14th IEEE Int. Conf. Fuzzy Syst. 2005. FUZZ '05., 2005.
- [25] M. Y. Ju, C. Sen Ouyang, and H. S. Chang, "Mean shift tracking using fuzzy color histogram," in 2010 International Conference on Machine Learning and Cybernetics, ICMLC 2010, 2010, vol. 6, pp. 2904–2908.
- [26] I. K. Vlachos and G. D. Sergiadis, "Intuitionistic fuzzy information Applications to pattern recognition," *Pattern Recognit. Lett.*, vol. 28, pp. 197–206, 2007.
- [27] G. Bailador and G. Trivino, "Pattern recognition using temporal fuzzy automata," *FUZZY SETS Syst.*, vol. 161, pp. 37–55, 2010.
- [28] H. Liu, D. J. Brown, and G. M. Coghill, "Fuzzy qualitative robot kinematics," *IEEE Trans. Fuzzy Syst.*, vol. 16, pp. 808–822, 2008.
- [29] P. K. Jamwal, S. Q. Xie, Y. H. Tsoi, and K. C. Aw, "Forward kinematics modelling of a parallel ankle rehabilitation robot using modified fuzzy inference," *Mech. Mach. Theory*, vol. 45, pp. 1537–1554, 2010.
- [30] Z. Song, J. Yi, D. Zhao, and X. Li, "A computed torque controller for uncertain robotic manipulator systems: Fuzzy approach," *Fuzzy Sets Syst.*, vol. 154, pp. 208–226, 2005.
- [31] M. K. Chang, "An adaptive self-organizing fuzzy sliding mode controller for a 2-DOF rehabilitation robot actuated by pneumatic muscle actuators," *Control Eng. Pract.*, vol. 18, pp. 13–22, 2010.
- [32] C.-T. Chen, C.-T. Lin, and S.-F. Huang, "A fuzzy approach for supplier evaluation and selection in supply chain management," *International Journal of Production Economics*, vol. 102. pp. 289–301, 2006.
- [33] D. Peidro, J. Mula, R. Poler, and J. L. Verdegay, "Fuzzy optimization for supply chain planning under supply, demand and process uncertainties," *Fuzzy Sets Syst.*, vol. 160, pp. 2640–2657, 2009.
- [34] C. S. Liu, L. R. Chen, B. Z. Li, S. K. Chen, and Z. S. Zeng, "Improvement of the twin rotor MIMO system tracking and transient response using fuzzy control technology," in 2006 1st IEEE Conference on Industrial Electronics and Applications, 2006.
- [35] C. W. Tao, J. S. Taur, and Y. C. Chen, "Design of a parallel distributed fuzzy LQR controller for the twin rotor multi-input multi-output system," *Fuzzy Sets Syst.*, vol. 161, pp. 2081–2103, 2010.
- [36] S. K. Nguang, P. Shi, and S. Ding, "Fault detection for uncertain fuzzy systems: An LMI approach," *IEEE Trans. Fuzzy Syst.*, vol. 15, pp. 1251–1262, 2007.
- [37] M. Abadeh, J. Habibi, and C. Lucas, "Intrusion detection using a fuzzy genetics-based learning algorithm," J. Netw. Comput. Appl., vol. 30, pp. 414–428, 2007.

- [38] I. Dikmen, M. T. Birgonul, and S. Han, "Using fuzzy risk assessment to rate cost overrun risk in international construction projects," *Int. J. Proj. Manag.*, vol. 25, pp. 494–505, 2007.
- [39] M. Takács, "Multilevel Fuzzy Approach to the Risk and Disaster Management," vol. 7, no. 4, pp. 91–102, 2010.
- [40] V. V. Srinivas, S. Tripathi, A. R. Rao, and R. S. Govindaraju, "Regional flood frequency analysis by combining self-organizing feature map and fuzzy clustering," *J. Hydrol.*, vol. 348, pp. 148–166, 2008.
- [41] S. J. Kalayathankal and G. Suresh Singh, "A fuzzy soft flood alarm model," *Math. Comput. Simul.*, vol. 80, pp. 887–893, 2010.
- [42] T. A. Jilani and S. M. A. Burney, "A refined fuzzy time series model for stock market forecasting," *Phys. A Stat. Mech. its Appl.*, vol. 387, pp. 2857–2862, 2008.
- [43] M. R. Hassan, "A combination of hidden Markov model and fuzzy model for stock market forecasting," *Neurocomputing*, vol. 72, pp. 3439–3446, 2009.
- [44] B. S. Yang, T. Han, and J. L. An, "ART-KOHONEN neural network for fault diagnosis of rotating machinery," *Mech. Syst. Signal Process.*, vol. 18, pp. 645–657, 2004.
- [45] Y. Wang, Q. Li, M. Chang, H. Chen, and G. Zang, "Research on fault diagnosis expert system based on the neural network and the fault tree technology," in *Procedia Engineering*, 2012, vol. 31, pp. 1206–1210.
- [46] J. Chen and T. C. Huang, "Applying neural networks to on-line updated PID controllers for nonlinear process control," *J. Process Control*, vol. 14, pp. 211–230, 2004.
- [47] Y. Song, Z. Chen, and Z. Yuan, "New chaotic PSO-based neural network predictive control for nonlinear process," *IEEE Trans. Neural Networks*, vol. 18, pp. 595–600, 2007.
- [48] S. S. Chiddarwar and N. Ramesh Babu, "Comparison of RBF and MLP neural networks to solve inverse kinematic problem for 6R serial robot by a fusion approach," *Eng. Appl. Artif. Intell.*, vol. 23, pp. 1083–1092, 2010.
- [49] A. T. Hasan, N. Ismail, A. M. S. Hamouda, I. Aris, M. H. Marhaban, and H. M. A. A. Al-Assadi, "Artificial neural network-based kinematics Jacobian solution for serial manipulator passing through singular configurations," *Adv. Eng. Softw.*, vol. 41, pp. 359–367, 2010.
- [50] R. Perfetti and E. Ricci, "Analog neural network for support vector machine learning.," *IEEE transactions on neural networks / a publication of the IEEE Neural Networks Council*, vol. 17. pp. 1085–1091, 2006.
- [51] M. Jändel, "A neural support vector machine.," Neural Netw., vol. 23, pp. 607–613, 2010.
- [52] A. Subasi and E. Ercelebi, "Classification of EEG signals using neural network and logistic regression," *Comput Methods Programs Biomed*, vol. 78, pp. 87–99, 2005.
- [53] S. M. Jadhav, S. L. Nalbalwar, and A. Ghatol, "Artificial Neural Network based cardiac arrhythmia classification using ECG signal data," in *Electronics and Information Engineering ICEIE 2010 International Conference On*, 2010, vol. 1, pp. V1–228 –V1–231.
- [54] S. N. Huang, K. K. Tan, and T. H. Lee, "Further result on a dynamic recurrent neural-networkbased adaptive observer for a class of nonlinear systems," *Automatica*, vol. 41, pp. 2161–2162, 2005.
- [55] E. Artyomov and O. Yadid-Pecht, "Modified high-order neural network for invariant pattern recognition," *Pattern Recognit. Lett.*, vol. 26, pp. 843–851, 2005.
- [56] S. L. Phung and A. Bouzerdoum, "A pyramidal neural network for visual pattern recognition," *IEEE Trans. Neural Networks*, vol. 18, pp. 329–343, 2007.
- [57] M. a Mazurowski, P. a Habas, J. M. Zurada, J. Y. Lo, J. a Baker, and G. D. Tourassi, "Training neural network classifiers for medical decision making: the effects of imbalanced datasets on classification performance.," *Neural Netw.*, vol. 21, pp. 427–36, 2008.
- [58] F. Amato, A. López, E. M. Peña-Méndez, P. Vaňhara, A. Hampl, and J. Havel, "Artificial neural networks in medical diagnosis," J. Appl. Biomed., vol. 11, pp. 47–58, 2013.

- 170 Fuzzy, Neural Network and Expert Systems Methodologies and Applications: A Review
- [59] K. Movagharnejad and M. Nikzad, "Modeling of tomato drying using artificial neural network," *Comput. Electron. Agric.*, vol. 59, pp. 78–85, 2007.
- [60] L. Yu, K. K. Lai, and S. Wang, "Multistage RBF neural network ensemble learning for exchange rates forecasting," in *Neurocomputing*, 2008, vol. 71, pp. 3295–3302.
- [61] A. A. Philip, "Artificial Neural Network Model for Forecasting Foreign Exchange Rate," *Int. J. Serv. Oper. Manag.*, vol. 1, pp. 110–118, 2011.
- [62] J. Ahmed, M. N. Jafri, J. Ahmad, and M. I. Khan, "Design and Implementation of a Neural Network for Real-Time Object Tracking," no. 6, pp. 1829–1832, 2007.
- [63] L. I. Perlovsky and R. W. Deming, "Neural networks for improved tracking," *IEEE Trans. Neural Networks*, vol. 18, pp. 1854–1857, 2007.
- [64] R. P. V. G. Prasad, K. R. Sudha, S. P. Rama, and S. N. S. V. S. Ramesh, "Software Effort Estimation using Radial Basis and Generalized Regression Neural Networks," *J. Comput.*, vol. 2, pp. 87–92, 2010.
- [65] I. Attarzadeh, A. Mehranzadeh, and A. Barati, "Proposing an Enhanced Artificial Neural Network Prediction Model to Improve the Accuracy in Software Effort Estimation," *Fourth Int. Conf. Comput. Intell.*, pp. 167–172, 2012.
- [66] F. Shahraki, M. A. A. Fanaei, and A. R. R. Arjomandzadeh, "Adaptive System Control with PID Neural Networks," *Chem. Eng. Trans.*, vol. 17, pp. 1395–1400, 2009.
- [67] H. Hu, L. Xu, and R. Wei, "Nonlinear adaptive neuro-PID controller design for greenhouse environment based on RBF network," in *Proceedings of the International Joint Conference on Neural Networks*, 2010.
- [68] I. Engedy and G. Horvath, "Artificial neural network based mobile robot navigation," in 2009 *IEEE International Symposium on Intelligent Signal Processing*, 2009, pp. 241–246.
- [69] P. Benavidez and M. Jamshidi, "Mobile robot navigation and target tracking system," 2011 6th Int. Conf. Syst. Syst. Eng., pp. 299–304, 2011.
- [70] T. Sun, H. Pei, Y. Pan, H. Zhou, and C. Zhang, "Neural network-based sliding mode adaptive control for robot manipulators," *Neurocomputing*, vol. 74, pp. 2377–2384, 2011.
- [71] H. Liu and T. Zhang, "Neural network-based robust finite-time control for robotic manipulators considering actuator dynamics," *Robot. Comput. Integr. Manuf.*, vol. 29, pp. 301–308, 2013.
- [72] T. Dierks and S. Jagannathan, "Output feedback control of a quadrotor UAV using neural networks.," *IEEE Trans. Neural Netw.*, vol. 21, no. 1, pp. 50–66, Jan. 2010.
- [73] M. Ö. Efe and S. Member, "Neural Network Assisted Computationally Simple PID Control of a Quadrotor UAV," *IEEE Trans. Ind. Informatics*, vol. 7, no. 2, pp. 354–361, 2011.
- [74] A. Rahideh, A. H. Bajodah, and M. H. Shaheed, "Real time adaptive nonlinear model inversion control of a twin rotor MIMO system using neural networks," *Eng. Appl. Artif. Intell.*, vol. 25, pp. 1289–1297, 2012.
- [75] B. Shahzad, "Selection of Suitable Evaluation Function Based on Win / Draw Parameter in Othello," pp. 802–806, 2012.
- [76] Y. Al-Ohali, B. Shahzad, and L. Alssum, "Selection of Efficient Evaluation Function for Othello," in *CONTECSI International Conference on Information Systems and Technology Management*, 2012.
- [77] J.-S. R. Jang, C.-T. Sun, and E. Mizutani, *Neuro-Fuzzy and Soft Computing: A Computational Approach to Learning and Machine Intelligence*. 1997, p. 614.
- [78] B. Dixon, "Applicability of neuro-fuzzy techniques in predicting ground-water vulnerability: A GIS-based sensitivity analysis," *J. Hydrol.*, vol. 309, pp. 17–38, 2005.
- [79] J. Shiri and O. Kisi, "Short-term and long-term streamflow forecasting using a wavelet and neuro-fuzzy conjunction model," *J. Hydrol.*, vol. 394, pp. 486–493, 2010.

- [80] S. Chavan, K. Shah, N. Dave, S. Mukherjee, A. Abraham, and S. Sanyal, "Adaptive neurofuzzy intrusion detection systems," *Int. Conf. Inf. Technol. Coding Comput. 2004. Proceedings. ITCC 2004.*, vol. 1, 2004.
- [81] A. N. Toosi and M. Kahani, "A new approach to intrusion detection based on an evolutionary soft computing model using neuro-fuzzy classifiers," *Comput. Commun.*, vol. 30, pp. 2201– 2212, 2007.
- [82] Y. J. Zhang, T. Y. Chai, H. Wang, J. Fu, L. Y. Zhang, and Y. G. Wang, "An Adaptive Generalized Predictive Control Method for Nonlinear Systems Based on ANFIS and Multiple Models," *Ieee Trans. Fuzzy Syst.*, vol. 18, pp. 1070–1082, 2010.
- [83] Y. Zhang, T. Chai, and H. Wang, "A nonlinear control method based on ANFIS and multiple models for a class of SISO nonlinear systems and its application.," *IEEE Trans. Neural Netw.*, vol. 22, pp. 1783–95, 2011.
- [84] M. Khezri, M. Jahed, and N. Sadati, "Neuro-fuzzy surface EMG pattern recognition for multifunctional hand prosthesis control," in *IEEE International Symposium on Industrial Electronics*, 2007, pp. 269–274.
- [85] Y. H. Lin and M. S. Tsai, "Application of neuro-fuzzy pattern recognition for Non-intrusive Appliance Load Monitoring in electricity energy conservation," in *IEEE International Conference on Fuzzy Systems*, 2012.
- [86] I. Güler and E. D. Ubeyli, "Adaptive neuro-fuzzy inference system for classification of EEG signals using wavelet coefficients.," J. Neurosci. Methods, vol. 148, pp. 113–121, 2005.
- [87] W. Y. Hsu, "EEG-based motor imagery classification using neuro-fuzzy prediction and wavelet fractal features," J. Neurosci. Methods, vol. 189, pp. 295–302, 2010.
- [88] F. Samadzadegan, A. Azizi, M. Hahn, and C. Lucas, "Automatic 3D object recognition and reconstruction based on neuro-fuzzy modelling," *ISPRS J. Photogramm. Remote Sens.*, vol. 59, pp. 255–277, 2005.
- [89] J. Y. Kim, M. Kim, S. Lee, J. Oh, S. Oh, and H. J. Yoo, "Real-time object recognition with neuro-fuzzy controlled workload-aware task pipelining," *IEEE Micro*, vol. 29, pp. 28–43, 2009.
- [90] A. Rezoug, S. Boudoua, and F. Hamerlain, "Fuzzy Logic Control for Manipulator Robot actuated by Pneumatic Artificial Muscles.," in *Journal of electrical systems Special*, 2009, vol. 9, pp. 1–6.
- [91] L. D. Khoa, D. Q. Truong, and K. K. Ahn, "Synchronization controller for a 3-R planar parallel pneumatic artificial muscle (PAM) robot using modified ANFIS algorithm," *Mechatronics*, vol. 23, pp. 462–479, 2013.
- [92] S. K. Pradhan, D. R. Parhi, and A. K. Panda, "Neuro-fuzzy technique for navigation of multiple mobile robots," *Fuzzy Optim. Decis. Mak.*, vol. 5, pp. 255–288, 2006.
- [93] W. Budiharto, A. Jazidie, and D. Purwanto, "Indoor Navigation Using Adaptive Neuro Fuzzy Controller for Servant Robot," *Comput. Eng. Appl. (ICCEA), 2010 Second Int. Conf.*, vol. 1, 2010.
- [94] N. Kannathal, C. M. Lim, U. Rajendra Acharya, and P. K. Sadasivan, "Cardiac state diagnosis using adaptive neuro-fuzzy technique," *Med. Eng. Phys.*, vol. 28, pp. 809–815, 2006.
- [95] K. Salahshoor, M. Kordestani, and M. S. Khoshro, "Fault detection and diagnosis of an industrial steam turbine using fusion of SVM (support vector machine) and ANFIS (adaptive neuro-fuzzy inference system) classifiers," *Energy*, vol. 35, pp. 5472–5482, 2010.
- [96] C. K. Lau, K. Ghosh, M. A. Hussain, and C. R. Che Hassan, "Fault diagnosis of Tennessee Eastman process with multi-scale PCA and ANFIS," *Chemom. Intell. Lab. Syst.*, vol. 120, pp. 1–14, 2013.

- 172 Fuzzy, Neural Network and Expert Systems Methodologies and Applications: A Review
- [97] T. Orlowska-Kowalska, M. Dybkowski, and K. Szabat, "Adaptive neuro-fuzzy control of the sensorless induction motor drive system," in *EPE-PEMC 2006: 12th International Power Electronics and Motion Control Conference, Proceedings*, 2007, pp. 1836–1841.
- [98] T. Orlowska-Kowalska, M. Dybkowski, and K. Szabat, "Adaptive sliding-mode neuro-fuzzy control of the two-mass induction motor drive without mechanical sensors," in *IEEE Transactions on Industrial Electronics*, 2010, vol. 57, pp. 553–564.
- [99] X. Huang, D. Ho, J. Ren, and L. F. Capretz, "Improving the COCOMO model using a neurofuzzy approach," *Appl. Soft Comput. J.*, vol. 7, pp. 29–40, 2007.
- [100] J. Wong, D. Ho, and L. F. Capretz, "An investigation of using neuro-fuzzy with software size estimation," in *Proceedings - International Conference on Software Engineering*, 2009, pp. 51–58.
- [101] Z. Liu, T. Li, and F. Xiong, "An improved ANFIS method and its application on agricultural information degree measurement," in *Proceedings - 2008 International Conference on MultiMedia and Information Technology, MMIT 2008*, 2008, pp. 78–81.
- [102] Q. Sheng, Z. Qing, X. Z. Gao, and Y. Shuanghe, "ANFIS controller for double inverted pendulum," in *IEEE International Conference on Industrial Informatics (INDIN)*, 2008, pp. 475–480.
- [103] R. C. Tatikonda, V. P. Battula, and V. Kumar, "Control of inverted pendulum using Adaptive Neuro Fuzzy Inference Structure (ANFIS)," in ISCAS 2010 - 2010 IEEE International Symposium on Circuits and Systems: Nano-Bio Circuit Fabrics and Systems, 2010, pp. 1348– 1351.
- [104] E. Abbasi and A. Abouec, "Stock Price Forecast by Using Neuro-Fuzzy Inference System," Int. J. Soc. Hum. Sci., vol. 2, pp. 631–634, 2008.
- [105] C. F. Liu, C. Y. Yeh, and S. J. Lee, "Application of type-2 neuro-fuzzy modeling in stock price prediction," *Appl. Soft Comput. J.*, vol. 12, pp. 1348–1358, 2012.
- [106] S. Soyguder and H. Alli, "An expert system for the humidity and temperature control in HVAC systems using ANFIS and optimization with Fuzzy Modeling Approach," *Energy Build.*, vol. 41, pp. 814–822, 2009.
- [107] S. F. Toha and M. O. Tokhi, "Dynamic nonlinear inverse-model based control of a twin rotor system using adaptive neuro-fuzzy inference system," in EMS 2009 - UKSim 3rd European Modelling Symposium on Computer Modelling and Simulation, 2009, pp. 107–111.
- [108] S. F. Toha and M. O. Tokhi, "ANFIS modelling of a twin rotor system using particle swarm optimisation and RLS," in 2010 IEEE 9th International Conference on Cybernetic Intelligent Systems, CIS 2010, 2010.
- [109] T. Y. Pai, T. J. Wan, S. T. Hsu, T. C. Chang, Y. P. Tsai, C. Y. Lin, H. C. Su, and L. F. Yu, "Using fuzzy inference system to improve neural network for predicting hospital wastewater treatment plant effluent," *Comput. Chem. Eng.*, vol. 33, pp. 1272–1278, 2009.
- [110] J. Wan, M. Huang, Y. Ma, W. Guo, Y. Wang, H. Zhang, W. Li, and X. Sun, "Prediction of effluent quality of a paper mill wastewater treatment using an adaptive network-based fuzzy inference system," *Appl. Soft Comput. J.*, vol. 11, pp. 3238–3246, 2011.
- [111] M. Hayati, A. Rezaei, M. Seifi, and A. Naderi, "Modeling and simulation of combinational CMOS logic circuits by ANFIS," *Microelectronics J.*, vol. 41, pp. 381–387, 2010.
- [112] S. Kurnaz, O. Cetin, and O. Kaynak, "Adaptive neuro-fuzzy inference system based autonomous flight control of unmanned air vehicles," *Expert Syst. Appl.*, vol. 37, pp. 1229– 1234, 2010.
- [113] M. Aghajarian and K. Kiani, "Inverse Kinematics solution of PUMA 560 robot arm using ANFIS," in URAI 2011 - 2011 8th International Conference on Ubiquitous Robots and Ambient Intelligence, 2011, pp. 574–578.

- [114] H. Chaudhary and R. Prasad, "INTELLIGENT INVERSE KINEMATIC CONTROL OF SCORBOT-ER V PLUS ROBOT MANIPULATOR," Int. J. Adv. Eng. Technol. IJAET, vol. Vol. 1, pp. 158–169, 2011.
- [115] C. Grosan and A. Abraham, "Rule-Based Expert Systems," Intell. Syst. Ref. Libr., vol. 17, pp. 149–185, 2011.
- [116] K. K. Li, G. J. Chen, T. S. Chung, and G. Q. Tang, "Distribution planning using a rule-based expert system approach," 2004 IEEE Int. Conf. Electr. Util. Deregulation, Restruct. Power Technol. Proc., vol. 2, 2004.
- [117] L. K. Soh, C. Tsatsoulis, D. Gineris, and C. Bertoia, "ARKTOS: An intelligent system for SAR sea ice image classification," *IEEE Trans. Geosci. Remote Sens.*, vol. 42, pp. 229–248, 2004.
- [118] I. Hatzilygeroudis and J. Prentzas, "Integrating (rules, neural networks) and cases for knowledge representation and reasoning in expert systems," *Expert Syst. Appl.*, vol. 27, pp. 63–75, 2004.
- [119] L. M. A. Valenzuela, J. M. Bentley, and R. D. Lorenz, "Expert system for integrated control and supervision of dry-end sections of paper machines," *IEEE Trans. Ind. Appl.*, vol. 40, pp. 680–691, 2004.
- [120] I. Hatzilygeroudis and J. Prentzas, "Using a hybrid rule-based approach in developing an intelligent tutoring system with knowledge acquisition and update capabilities," *Expert Syst. Appl.*, vol. 26, pp. 477–492, 2004.
- [121] M. H. Zadeh and E. Kubica, "Modelling haptic devices using a rule-based expert system," in HAVE 2005: IEEE International Workshop on Haptic Audio Visual Environments and their Applications, 2005, vol. 2005, pp. 83–88.
- [122] H. Wang, S. Kwong, Y. Jin, W. Wei, and K. F. Man, "Agent-based evolutionary approach for interpretable rule-based knowledge extraction," *IEEE Trans. Syst. Man Cybern. Part C Appl. Rev.*, vol. 35, pp. 143–155, 2005.
- [123] E. Lamma, P. Mello, A. Nanetti, F. Riguzzi, S. Storari, and G. Valastro, "Artificial intelligence techniques for monitoring dangerous infections.," *IEEE Trans. Inf. Technol. Biomed.*, vol. 10, pp. 143–155, 2006.
- [124] E. Seto, K. J. Leonard, J. A. Cafazzo, J. Barnsley, C. Masino, and H. J. Ross, "Developing healthcare rule-based expert systems: Case study of a heart failure telemonitoring system," *Int. J. Med. Inform.*, vol. 81, pp. 556–565, 2012.
- [125] T. Kurtoglu and I. Y. Tumer, "A Graph-Based Fault Identification and Propagation Framework for Functional Design of Complex Systems," *Journal of Mechanical Design*, vol. 130. p. 051401, 2008.
- [126] J. Qu and L. Liang, "A production rule based expert system for electronic control automatic transmission fault diagnosis," in *Proceedings - 2009 International Conference on Information Engineering and Computer Science, ICIECS 2009*, 2009.
- [127] A. Jain, R. Balasubramanian, S. C. Tripathy, and Y. Kawazoe, "Topological observability analysis using heuristic rule based expert system," 2006 IEEE Power Eng. Soc. Gen. Meet., 2006.
- [128] S. Peddabachigari, A. Abraham, C. Grosan, and J. Thomas, "Modeling intrusion detection system using hybrid intelligent systems," *J. Netw. Comput. Appl.*, vol. 30, pp. 114–132, 2007.
- [129] M. V. Butz, "Combining gradient-based with evolutionary online learning: An introduction to learning classifier systems," in *Proceedings - 7th International Conference on Hybrid Intelligent Systems*, HIS 2007, 2007, pp. 12–17.
- [130] Z. J. Zhou, C. H. Hu, J. B. Yang, D. L. Xu, and D. H. Zhou, "Online updating belief rule based system for pipeline leak detection under expert intervention," *Expert Syst. Appl.*, vol. 36, pp. 7700–7709, 2009.

- 174 Fuzzy, Neural Network and Expert Systems Methodologies and Applications: A Review
- [131] M. Simard, N. Ueffing, P. Isabelle, and R. Kuhn, "Rule-based Translation With Statistical Phrase-based Post-editing," ACL 2007 Second Work. Stat. Mach. Transl., pp. 203–206, 2007.
- [132] C. Snae and P. Pongcharoen, "Automatic rule-based expert system for English to Thai transcription," in *Proceedings of the 3rd IASTED International Conference on Advances in Computer Science and Technology, ACST 2007*, 2007, pp. 342–347.
- [133] M. Nilsson, J. Van Laere, T. Ziemke, and J. Edlund, "Extracting rules from expert operators to support situation awareness in maritime surveillance," in *Proceedings of the 11th International Conference on Information Fusion, FUSION 2008*, 2008.
- [134] H. Chtourou and M. Haouari, "A two-stage-priority-rule-based algorithm for robust resourceconstrained project scheduling," *Comput. & amp; Ind. Eng.*, vol. 55, pp. 183–194, 2008.
- [135] J. H. Chen and P. Baldi, "No electron left behind: A rule-based expert system to predict chemical reactions and reaction mechanisms," J. Chem. Inf. Model., vol. 49, pp. 2034–2043, 2009.
- [136] S. K. Sarma and K. R. Singh, "An Expert System for diagnosis of diseases in Rice Plant," Int. J. Artif. Intell., vol. 1, pp. 26–31, 2010.
- [137] I. Borlea, G. Vuc, D. Jigoria-Oprea, A. Kilyeni, C. Barbulescu, and T. Slavici, "A rule-based expert system for steady state diagnosis of electrical distribution networks," in *Proceedings of* the Mediterranean Electrotechnical Conference - MELECON, 2010, pp. 142–147.
- [138] N. Lai, W. Dong, J. Wang, X. Xiao, and J. Lai, "Application of rule based expert system to sand control in oil fields," in *Proceedings - 2012 5th International Conference on Intelligent Computation Technology and Automation, ICICTA 2012*, 2012, pp. 110–113.
- [139] P. A. Jaques, H. Seffrin, G. Rubi, F. De Morais, C. Ghilardi, I. I. Bittencourt, and S. Isotani, "Rule-based expert systems to support step-by-step guidance in algebraic problem solving: The case of the tutor PAT2Math," *Expert Syst. Appl.*, vol. 40, pp. 5456–5465, 2013.
- [140] M. De la Sen, J. J. Miñambres, A. J. Garrido, A. Almansa, and J. C. Soto, "Basic theoretical results for expert systems. Application to the supervision of adaptation transients in planar robots," *Artif. Intell.*, vol. 152, pp. 173–211, 2004.
- [141] A. Bouguerra, L. Karlsson, and A. Saffiotti, "Semantic knowledge-based execution monitoring for mobile robots," in *Proceedings - IEEE International Conference on Robotics and Automation*, 2007, pp. 3693–3698.
- [142] H. C. Huang, "Designing a knowledge-based system for strategic planning: A balanced scorecard perspective," *Expert Syst. Appl.*, vol. 36, pp. 209–218, 2009.
- [143] A. Berrais, "A knowledge-based expert system for earthquake resistant design of reinforced concrete buildings," *Expert Systems with Applications*, vol. 28. pp. 519–530, 2005.
- [144] W. Wen, W. K. Wang, and C. H. Wang, "A knowledge-based intelligent decision support system for national defense budget planning," *Expert Systems with Applications*, vol. 28. pp. 55–66, 2005.
- [145] S. Piramuthu, "Knowledge-based framework for automated dynamic supply chain configuration," *Eur. J. Oper. Res.*, vol. 165, pp. 219–230, 2005.
- [146] C. Nan, F. Khan, and M. T. Iqbal, "Real-time fault diagnosis using knowledge-based expert system," *Process Saf. Environ. Prot.*, vol. 86, pp. 55–71, 2008.
- [147] C. G. Siontorou, F. A. Batzias, and V. Tsakiri, "A knowledge-based approach to online fault diagnosis of FET biosensors," *IEEE Trans. Instrum. Meas.*, vol. 59, pp. 2345–2364, 2010.
- [148] K. Saleem, A. Derhab, J. Al-muhtadi, and B. Shahzad, "Computers in Human Behavior Human-oriented design of secure Machine-to-Machine communication system for e-Healthcare society," *Comput. Human Behav.*, 2014.
- [149] D. K. S. Sanjeev Kumar Jha, "Development of knowledge Base Expert System for Natural treatment of Diabetes disease," *Int. J. Adv. Comput. Sci. Appl.*, vol. 3, 2012.

- [150] W. Wen, "A knowledge-based intelligent electronic commerce system for selling agricultural products," *Comput. Electron. Agric.*, vol. 57, pp. 33–46, 2007.
- [151] W. Wen, Y. H. Chen, and I. C. Chen, "A knowledge-based decision support system for measuring enterprise performance," *Knowledge-Based Syst.*, vol. 21, pp. 148–163, 2008.
- [152] W. Leigh, C. J. Frohlich, S. Hornik, R. L. Purvis, and T. L. Roberts, "Trading with a stock chart heuristic," *IEEE Trans. Syst. Man, Cybern. Part ASystems Humans*, vol. 38, pp. 93–104, 2008.
- [153] M. R. Aniba, S. Siguenza, A. Friedrich, F. Plewniak, O. Poch, A. Marchler-Bauer, and J. D. Thompson, "Knowledge-based expert systems and a proof-of-concept case study for multiple sequence alignment construction and analysis," *Briefings in Bioinformatics*, vol. 10. pp. 11–23, 2009.
- [154] S. Sulaiman, H. Mohamed, M. R. M. Arshad, N. A. Rashid, and U. K. Yusof, "Hajj-QAES: A knowledge-based expert system to support hajj pilgrims in decision making," in *ICCTD 2009 -2009 International Conference on Computer Technology and Development*, 2009, vol. 1, pp. 442–446.
- [155] D. M. Oliver, R. D. Fish, M. Winter, C. J. Hodgson, A. L. Heathwaite, and D. R. Chadwick, "Valuing local knowledge as a source of expert data: Farmer engagement and the design of decision support systems," *Environ. Model. Softw.*, vol. 36, pp. 76–85, 2012.
- [156] İ. Güler, A. Demirhan, and R. Karakış, "Interpretation of MR images using self-organizing maps and knowledge-based expert systems," *Digit. Signal Process.*, vol. 19, no. 4, pp. 668– 677, Jul. 2009.
- [157] P. de Almeida, "A knowledge-based approach to the iris segmentation problem," *Image Vis. Comput.*, vol. 28, pp. 238–245, 2010.
- [158] S. Rahman, F. Khan, B. Veitch, and P. Amyotte, "ExpHAZOP+: Knowledge-based expert system to conduct automated HAZOP analysis," J. Loss Prev. Process Ind., vol. 22, pp. 373– 380, 2009.
- [159] M. R. Aniba, O. Poch, A. Marchler-bauer, and J. D. Thompson, "AlexSys: A knowledge-based expert system for multiple sequence alignment construction and analysis," *Nucleic Acids Res.*, vol. 38, pp. 6338–6349, 2010.
- [160] S. Alhawari, L. Karadsheh, A. Nehari Talet, and E. Mansour, "Knowledge-Based Risk Management framework for Information Technology project," *Int. J. Inf. Manage.*, vol. 32, pp. 50–65, 2012.
- [161] I. A. R. Al-Ani, L. M. Sidek, M. N. M. Desa, and N. E. A. Basri, "Knowledge-based Expert System for Stormwater Management in Malaysia," *Journal of Environmental Science and Technology*, vol. 5, pp. 381–388, 2012.
- [162] M. Wooldridge and N. R. Jennings, "Intelligent agents: theory and practice," *The Knowledge Engineering Review*, vol. 10. p. 115, 1995.
- [163] A. J. Thomson and I. Willoughby, "A web-based expert system for advising on herbicide use in Great Britain," *Comput. Electron. Agric.*, vol. 42, pp. 43–49, 2004.
- [164] H. Z. Alibaba and M. B. Özdeniz, "A building elements selection system for architects," *Build. Environ.*, vol. 39, pp. 307–316, 2004.
- [165] M. A. Shirazi and J. Soroor, "An intelligent agent-based architecture for strategic information system applications," *Knowledge-Based Syst.*, vol. 20, pp. 726–735, 2007.
- [166] R. S. T. Lee, "iJADE stock advisor: An intelligent agent based stock prediction system using hybrid RBF recurrent network," *IEEE Trans. Syst. Man, Cybern. Part ASystems Humans.*, vol. 34, pp. 421–427, 2004.
- [167] Y. Wang and L. Fang, "Design of an intelligent agent-based supply chain simulation system," in Conference Proceedings - IEEE International Conference on Systems, Man and Cybernetics, 2007, pp. 1836–1841.

- 176 Fuzzy, Neural Network and Expert Systems Methodologies and Applications: A Review
- [168] I. Smeureanu, G. Ruxanda, A. Diosteanu, C. Delcea, and L. A. Cotfas, "Intelligent agents and risk based model for supply chain management," *Technological and Economic Development of Economy*, vol. 18. pp. 452–469, 2012.
- [169] C. S. J. Dong and A. Srinivasan, "Agent-enabled service-oriented decision support systems," *Decis. Support Syst.*, vol. 55, pp. 364–373, 2013.
- [170] R. Govindu and R. B. Chinnam, "MASCF: A generic process-centered methodological framework for analysis and design of multi-agent supply chain systems," *Comput. Ind. Eng.*, vol. 53, pp. 584–609, 2007.
- [171] M. Zhang, J. Tang, and J. Fulcher, "Agent-based grid computing," *Stud. Comput. Intell.*, vol. 115, pp. 439–483, 2008.
- [172] S. Gao and D. Xu, "Conceptual modeling and development of an intelligent agent-assisted decision support system for anti-money laundering," *Expert Syst. Appl.*, vol. 36, pp. 1493– 1504, 2009.
- [173] L. Li, "An intelligent tutoring system based on agent," 2009.
- [174] S. Ke and X. Lu, "Study on intelligent tutoring system based on multi-agents," in *Proceedings* 2010 6th International Conference on Natural Computation, ICNC 2010, 2010, vol. 6, pp. 2948–2952.
- [175] I. I. Bittencourt, E. Costa, M. Silva, and E. Soares, "A computational model for developing semantic web-based educational systems," *Knowledge-Based Syst.*, vol. 22, pp. 302–315, 2009.
- [176] R. Gowri, S. Kanmani, and T. T. S. Kumar, "Agent Based Adaptive Learning System," in trends in computer science, engineering and information technology, 2011, vol. 204, pp. 423– 431.
- [177] M. K. Kouluri and R. K. Pandey, "Intelligent agent based micro grid control," in IAMA 2011 -2011 2nd International Conference on Intelligent Agent and Multi-Agent Systems, 2011, pp. 62–66.